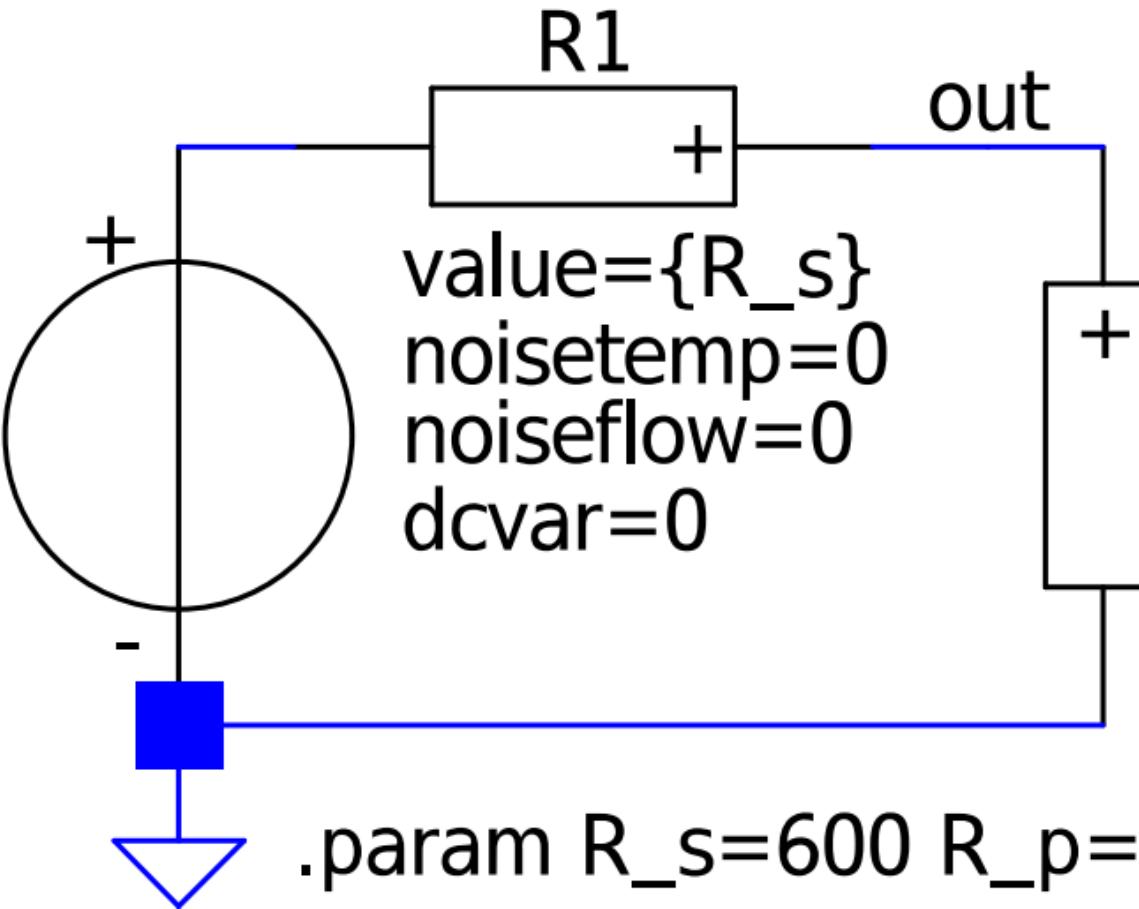


The noise of R1 is modeled in V1

V1
value=0
dc=0
dcvar=0
noise={4*k*T*R_s}



.param R_s=600 R_p=1k f_ell=10