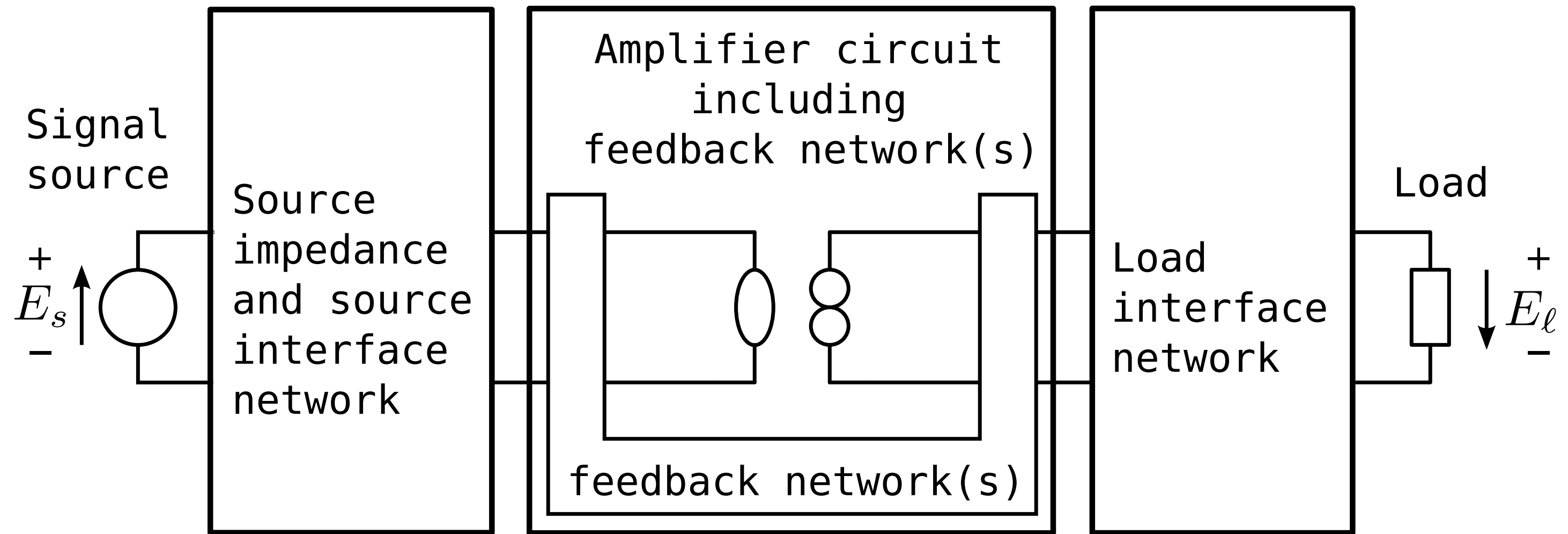


# **Structured Electronic Design**

## Noise Design of Input Stage MOS in Feedback Amplifiers

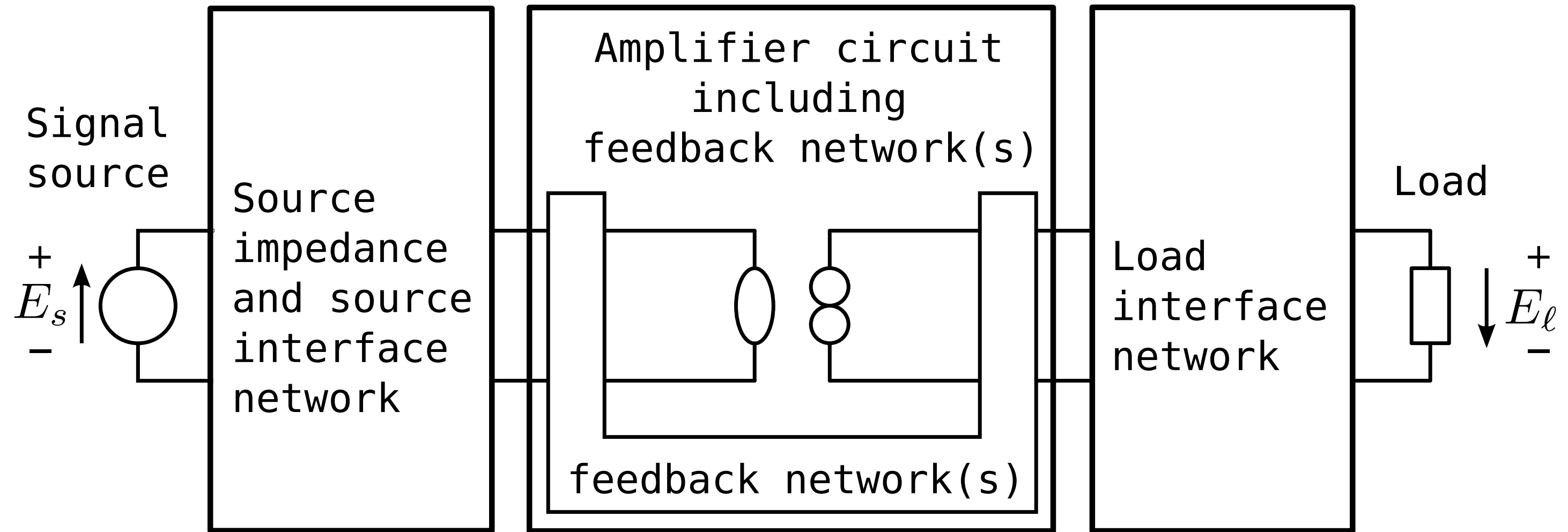
*Anton J.M. Montagne*

# Structure Feedback Amplifier



Known at the start of the controller's noise design

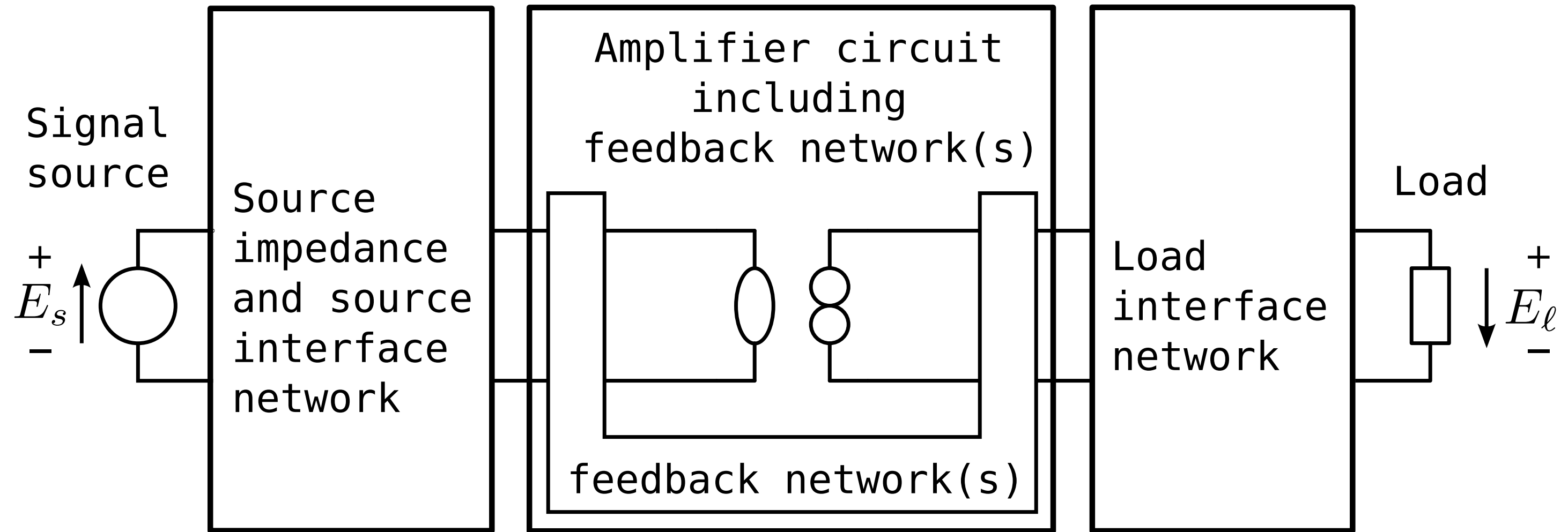
# Structure Feedback Amplifier



Known at the start of the controller's noise design

Source impedance

# Structure Feedback Amplifier

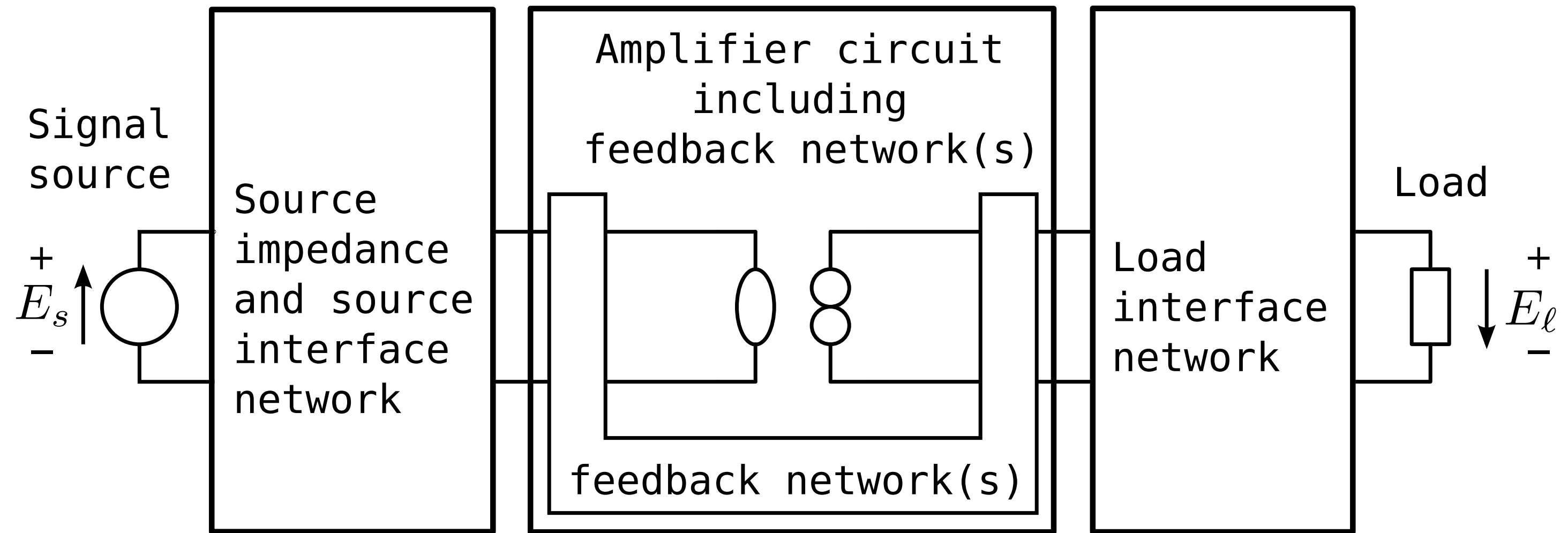


Known at the start of the controller's noise design

Source impedance

Source interface network

# Structure Feedback Amplifier



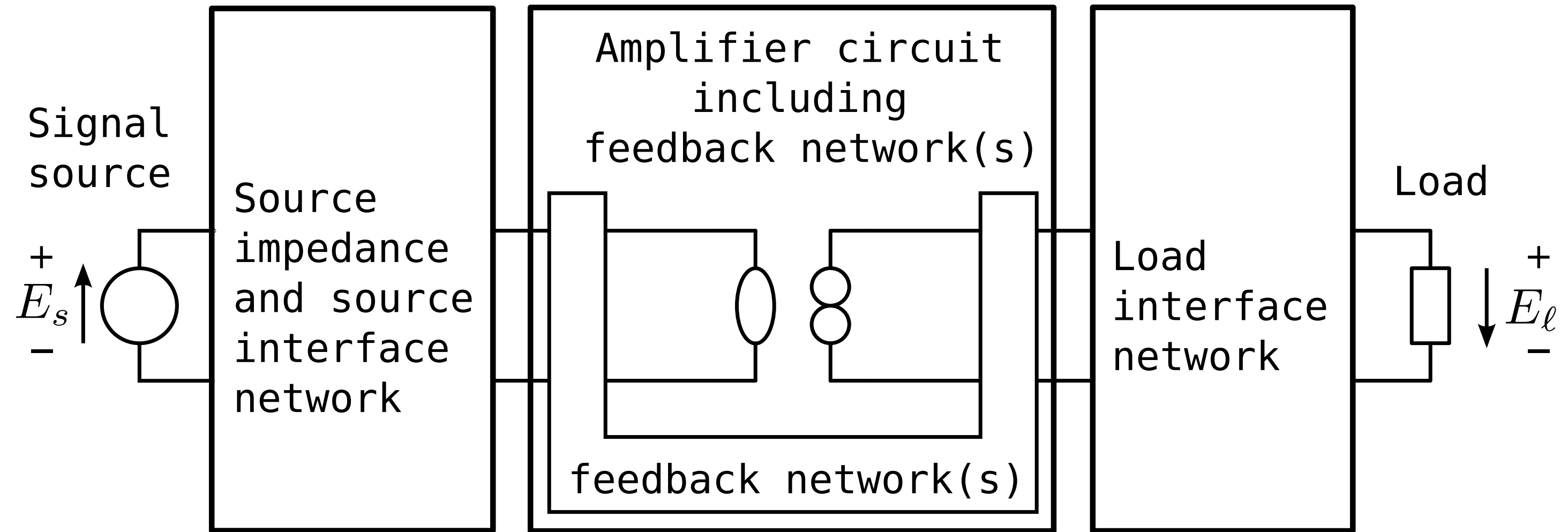
Known at the start of the controller's noise design

Source impedance

Load impedance

Source interface network

# Structure Feedback Amplifier

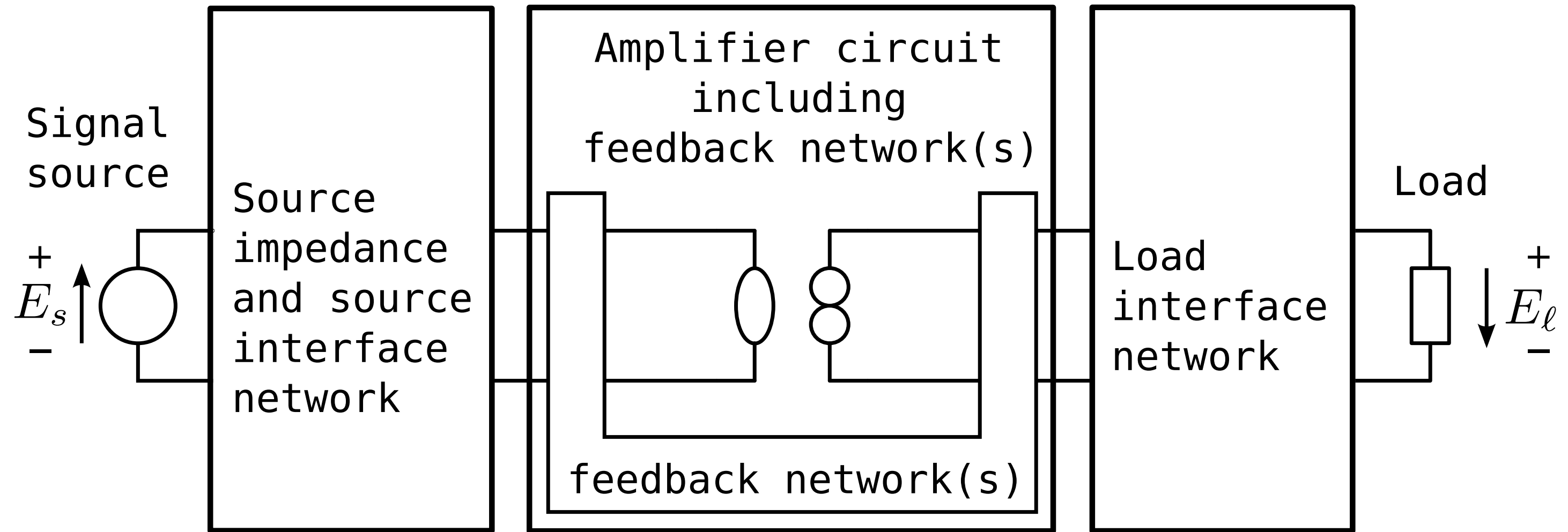


Known at the start of the controller's noise design

Source impedance  
Load impedance

Source interface network  
Load interface network

# Structure Feedback Amplifier



Known at the start of the controller's noise design

Source impedance

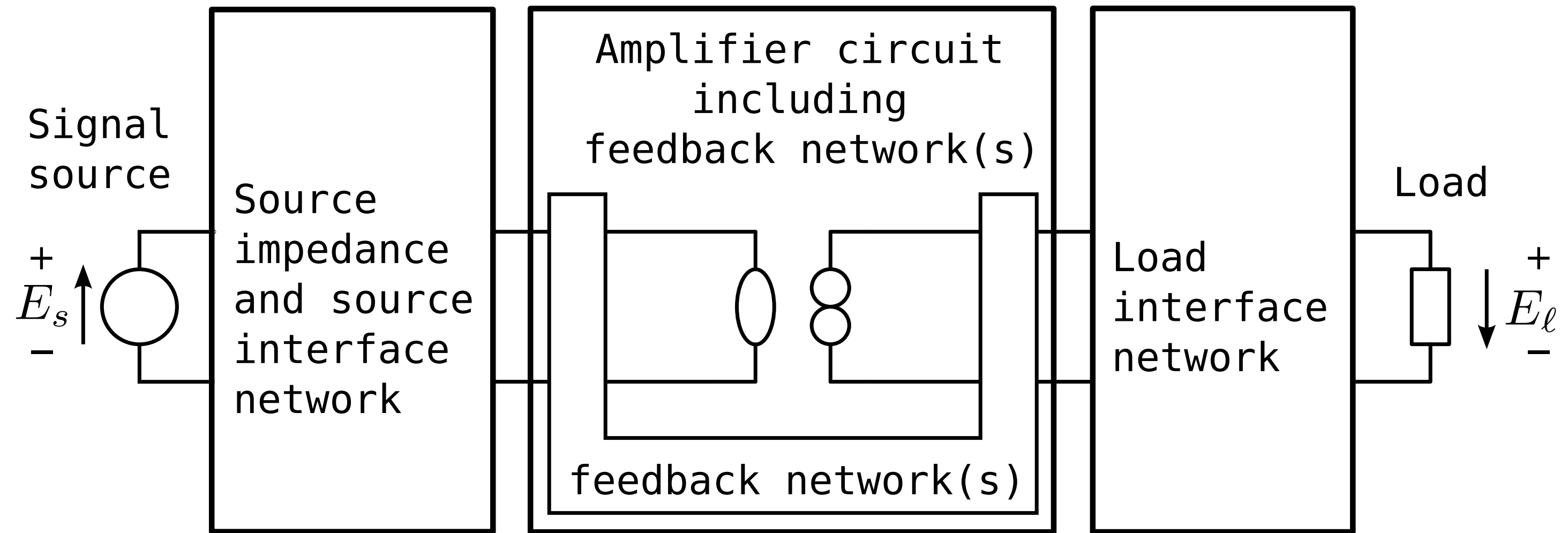
Load impedance

Feedback network(s)

Source interface network

Load interface network

# Structure Feedback Amplifier

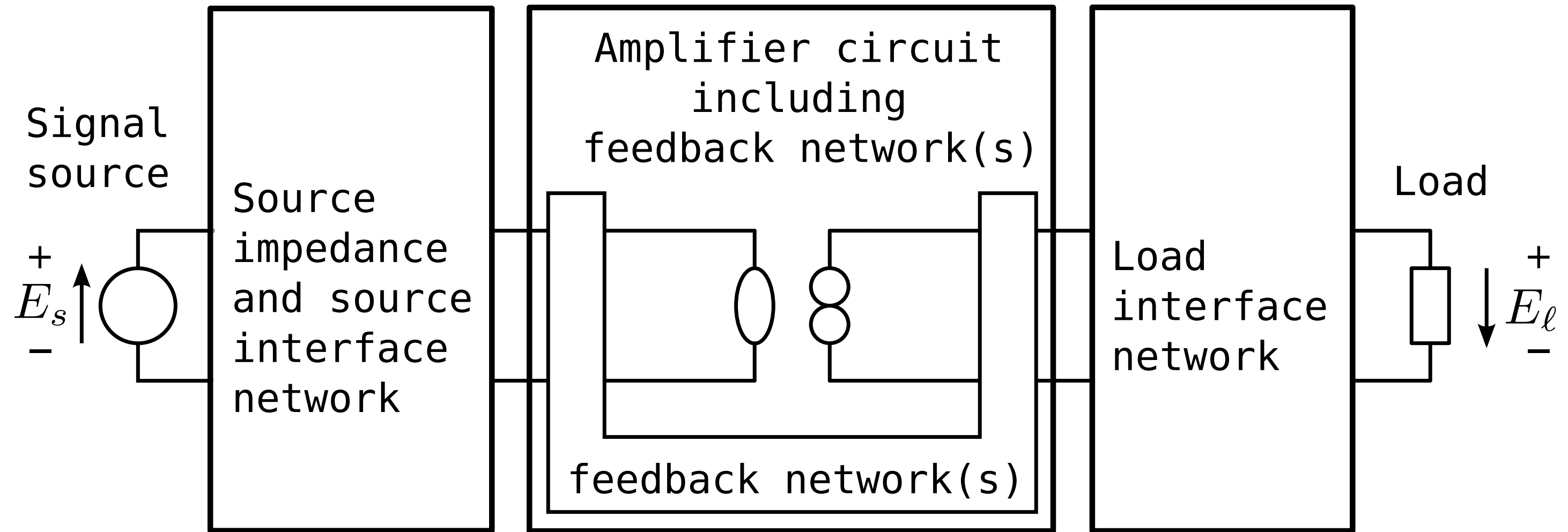


Known at the start of the controller's noise design

Source impedance  
Load impedance  
Feedback network(s)

Source interface network  
Load interface network  
Output noise weighting function

# Structure Feedback Amplifier

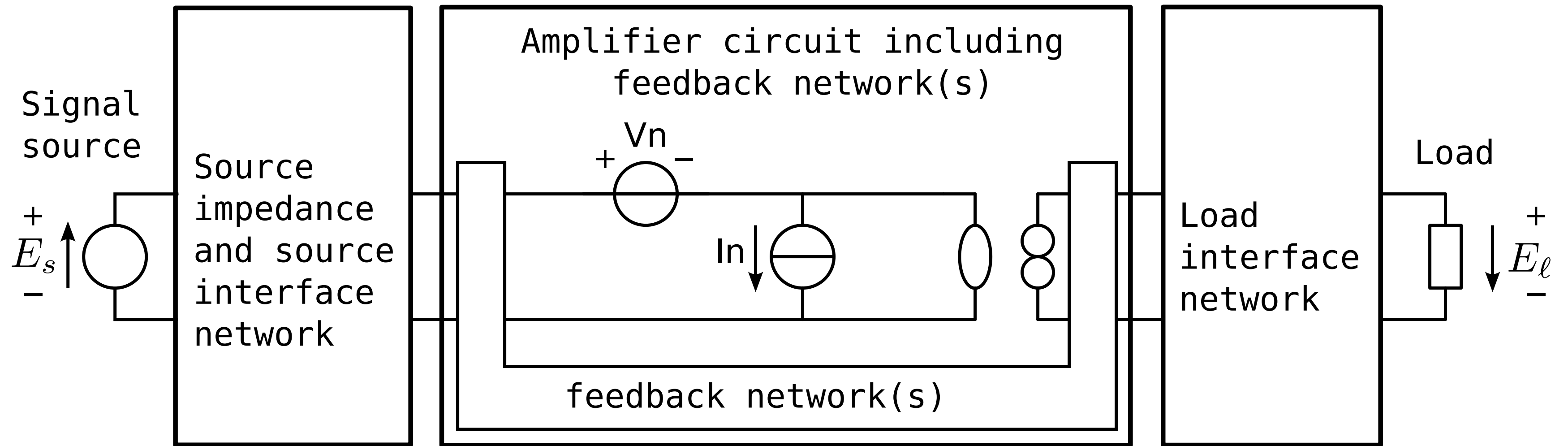


Known at the start of the controller's noise design

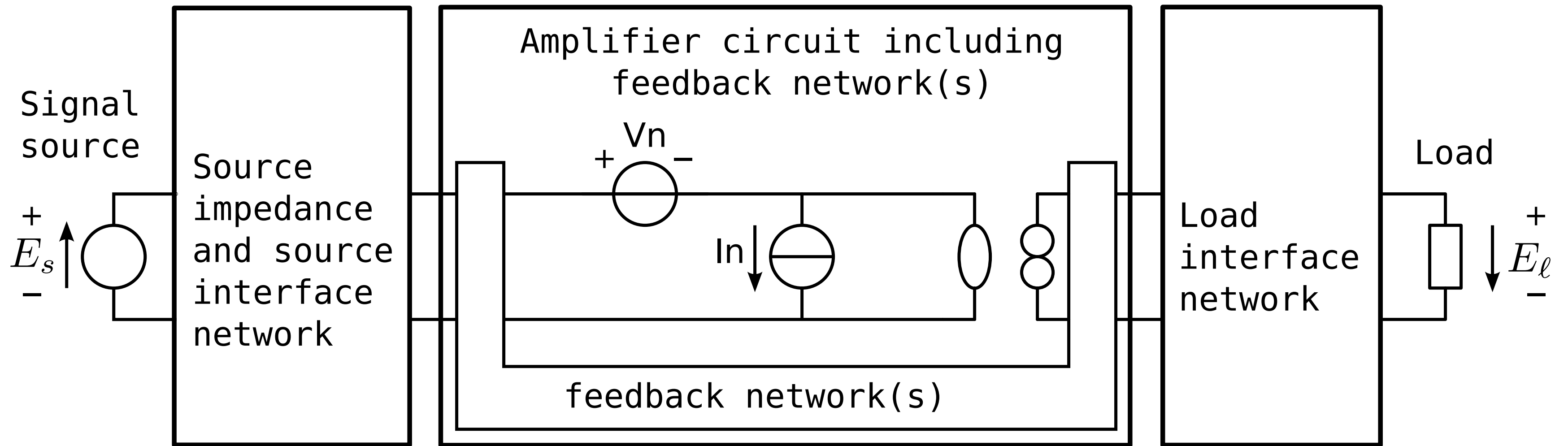
Source impedance  
Load impedance  
Feedback network(s)

Source interface network  
Load interface network  
Output noise weighting function

# Noise Transfer Functions

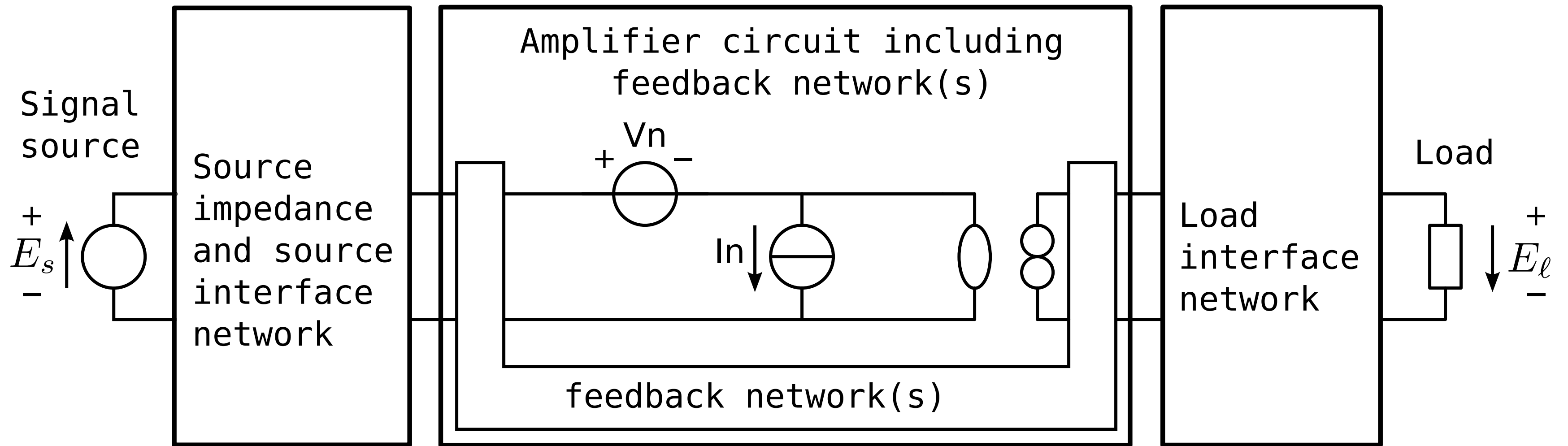


# Noise Transfer Functions



$H_v(f)$ : Transfer function from  $V_n$  to the output noise  $e_{\ell_n}$

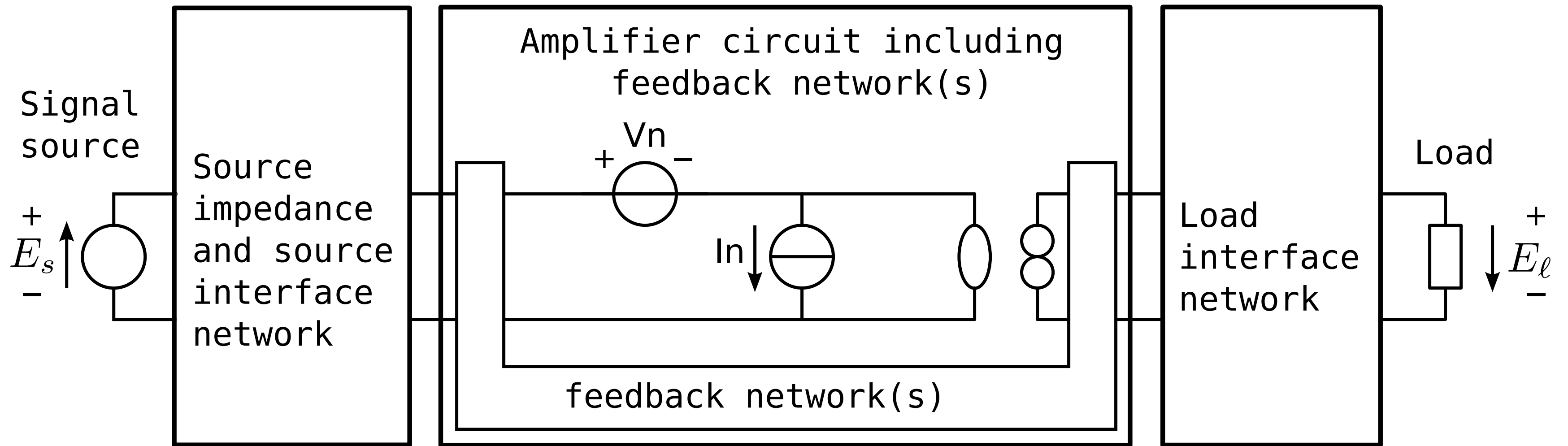
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# Noise Transfer Functions

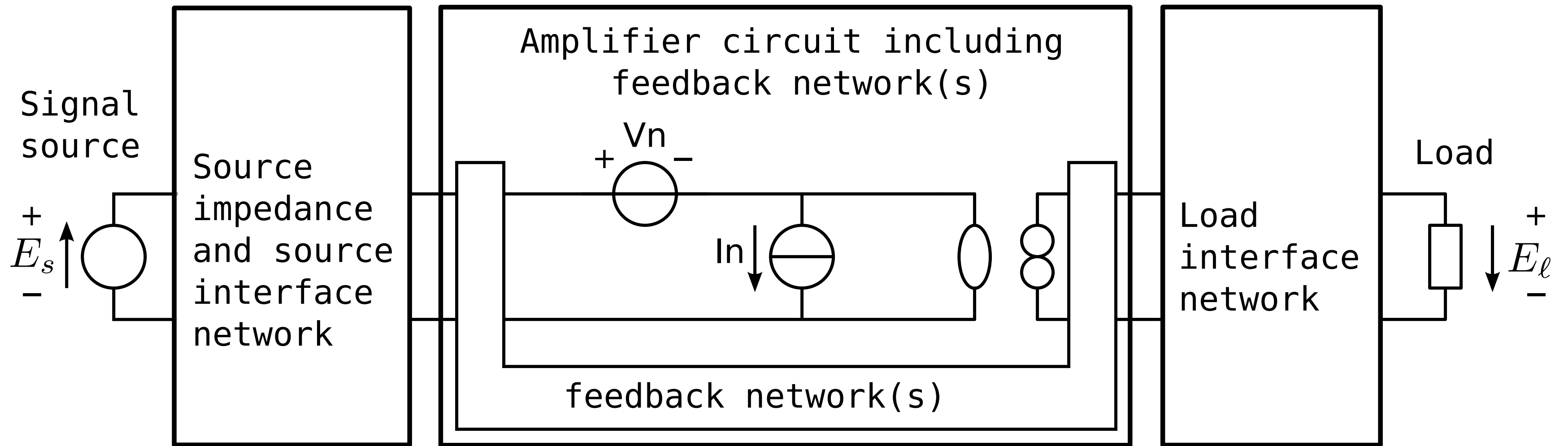


$H_v(f)$ : Transfer function from  $V_n$  to the output noise  $e_{\ell_n}$

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$\frac{H_i(f)}{H_v(f)} = Z_n(f)$ : Driving-point impedance at nullor input.

# Noise Transfer Functions



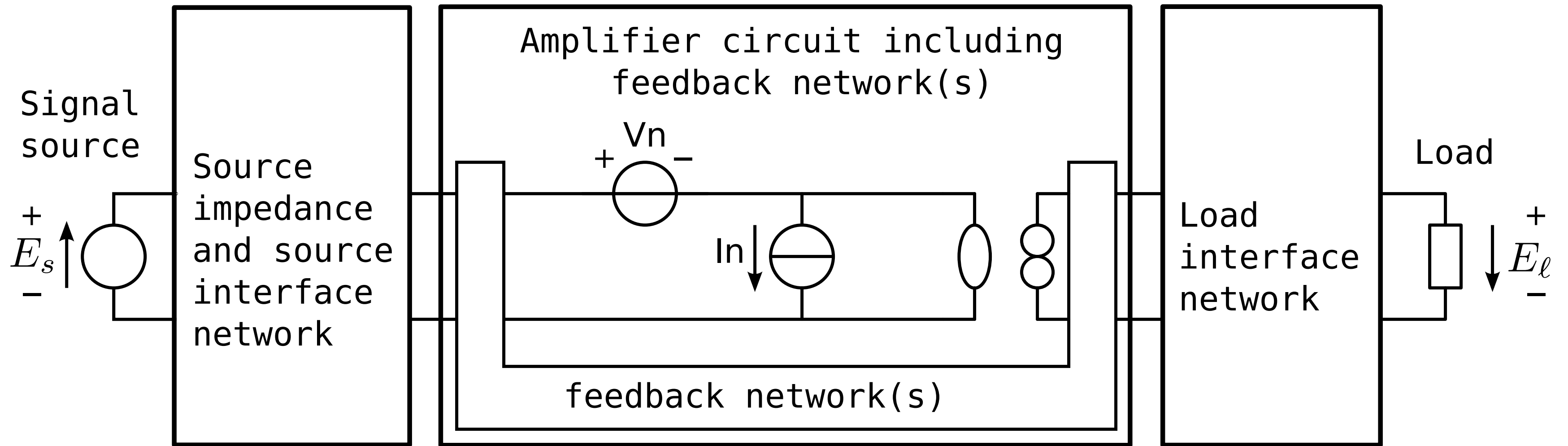
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$W(f)$ : Noise weighting function

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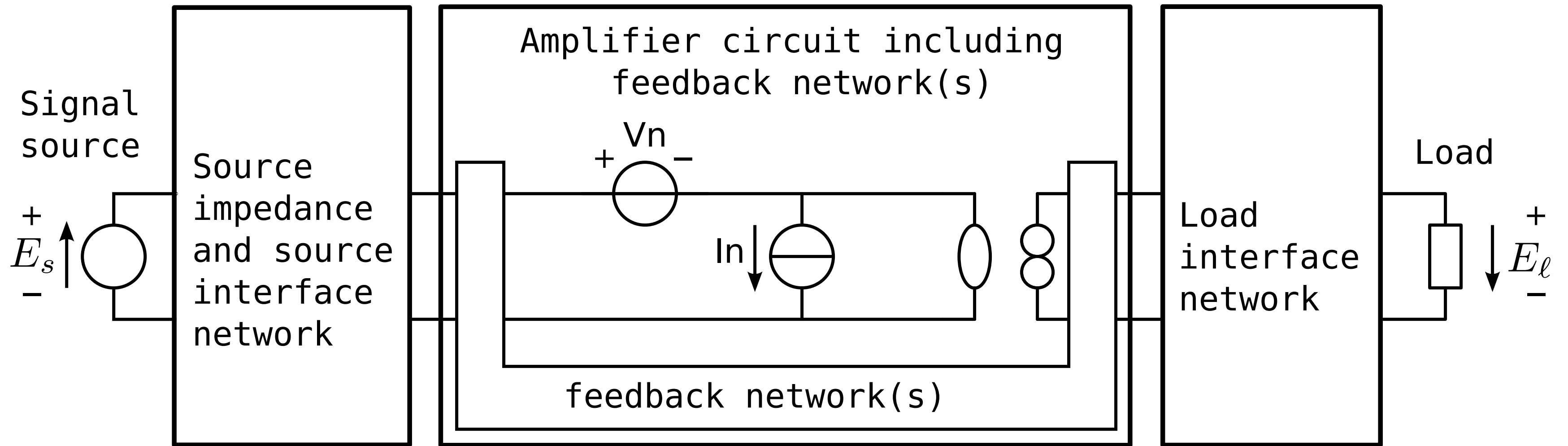
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$$e_{\ell_n}^2 = \int_{f_{\min}}^{f_{\max}} S_{v_n} |H_v(f)W(f)|^2 df + \int_{f_{\min}}^{f_{\max}} S_{i_n} |H_i(f)W(f)|^2 df + \int_{f_{\min}}^{f_{\max}} S_0 |W(f)|^2 df$$

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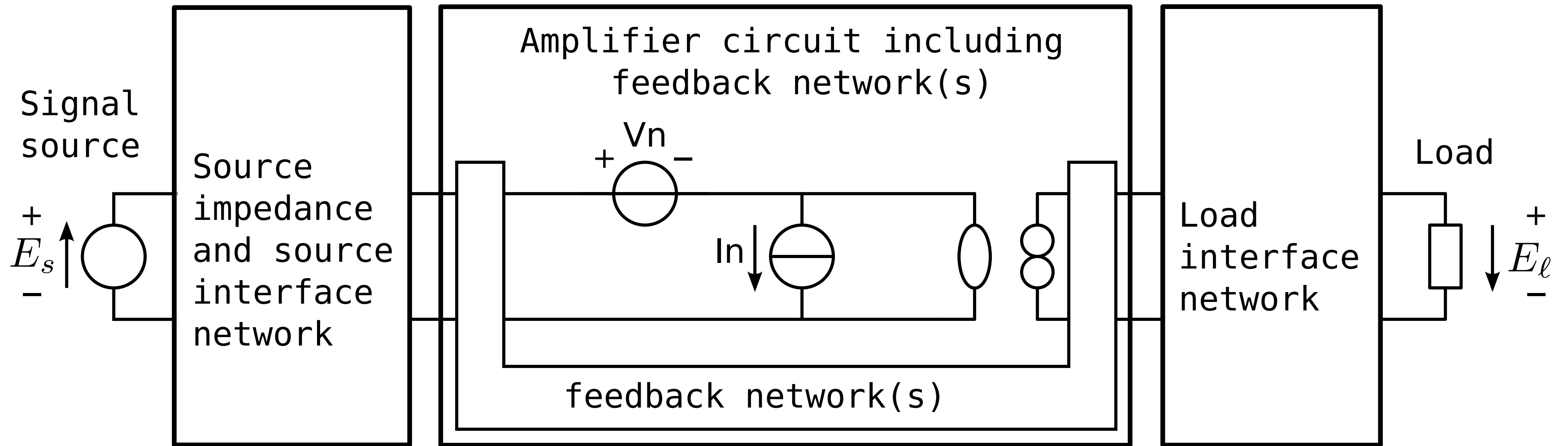
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Contribution of  $V_n$  to  
the weighted output noise

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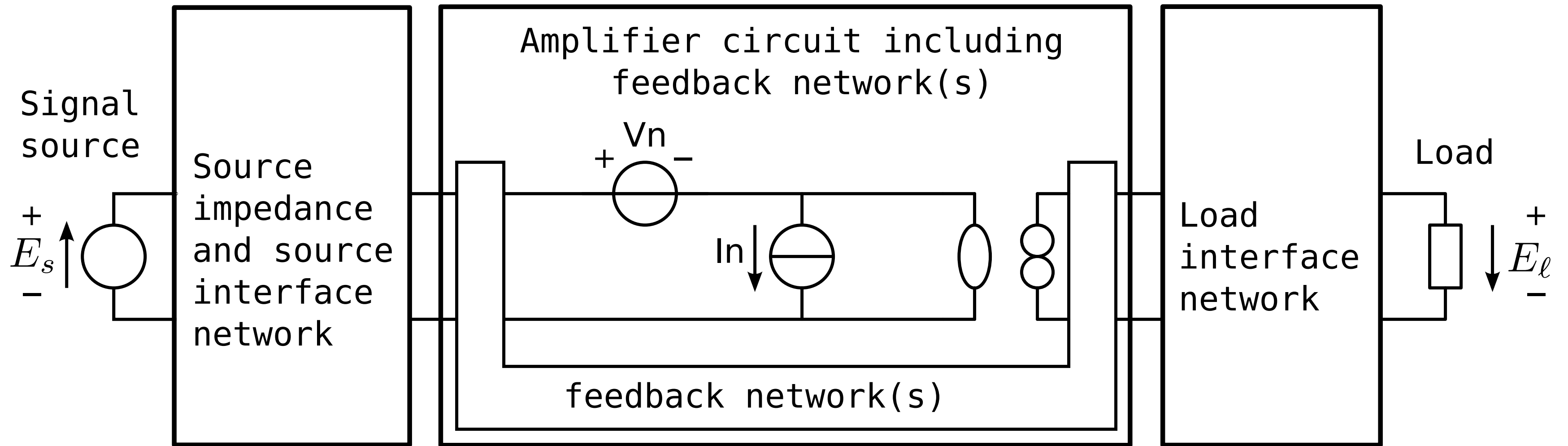
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Contribution of  $V_n$  to the weighted output noise

Contribution of  $I_n$  to the weighted output noise

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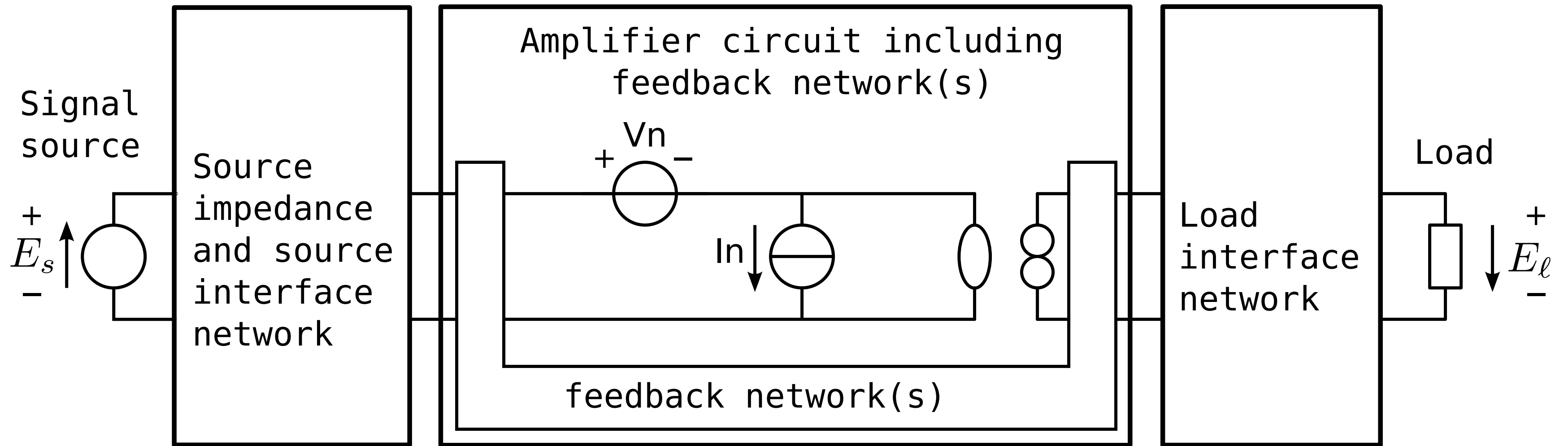
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Contribution of  $V_n$  to the weighted output noise
Contribution of  $I_n$  to the weighted output noise
Contribution of the source, the feedback and the interface network(s) to the weighted output noise

# Noise Transfer Functions



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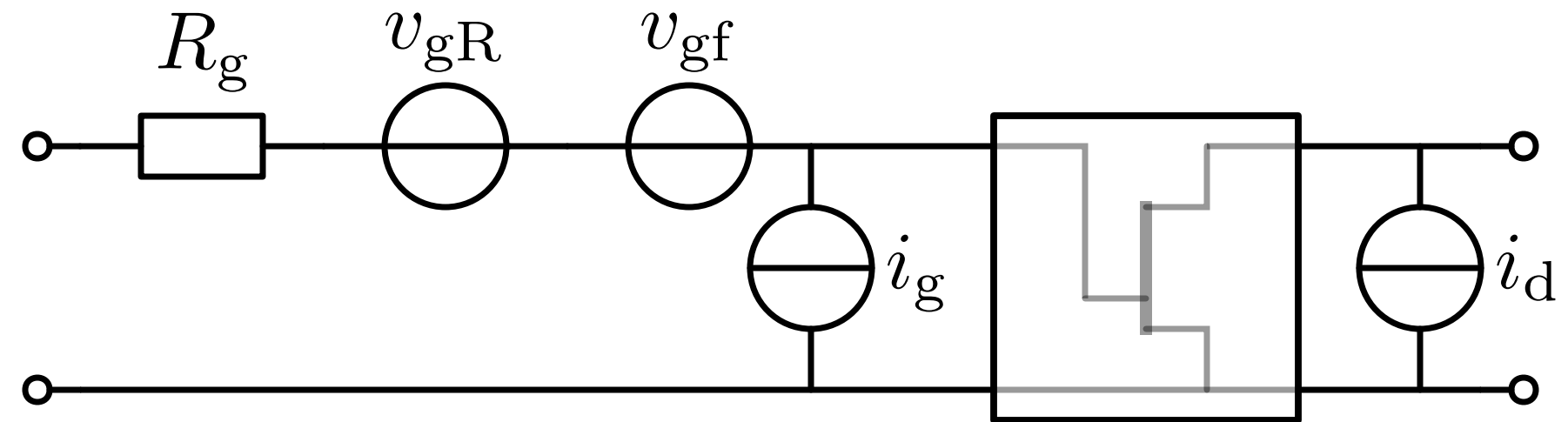
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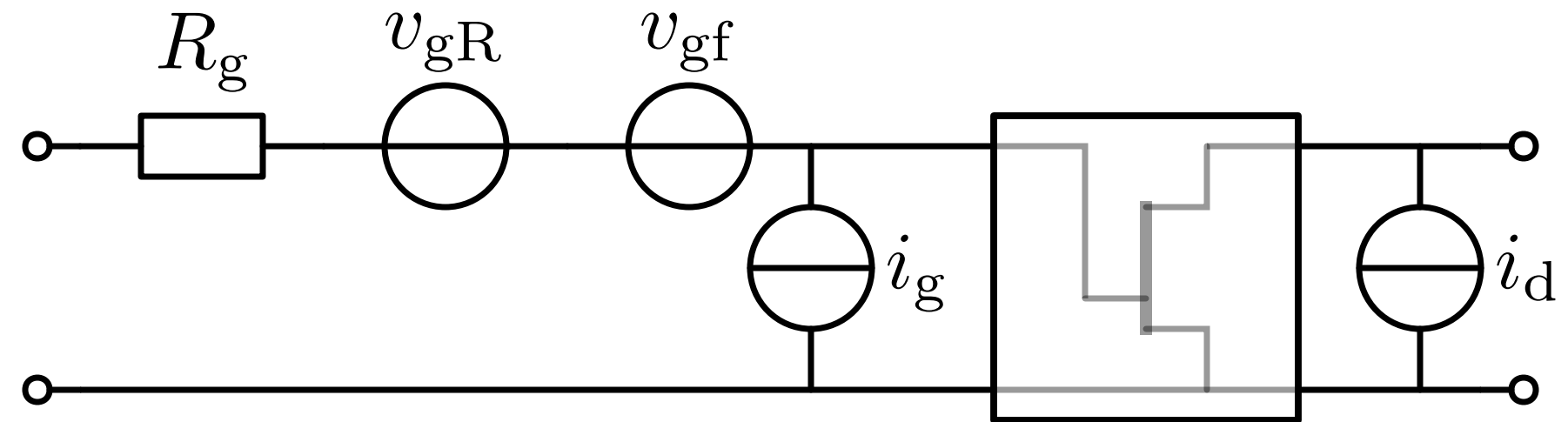
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Contribution of  $I_n$  to the weighted output noise
Contribution of the source, the feedback and the interface network(s) to the weighted output noise

# MOS Noise Model

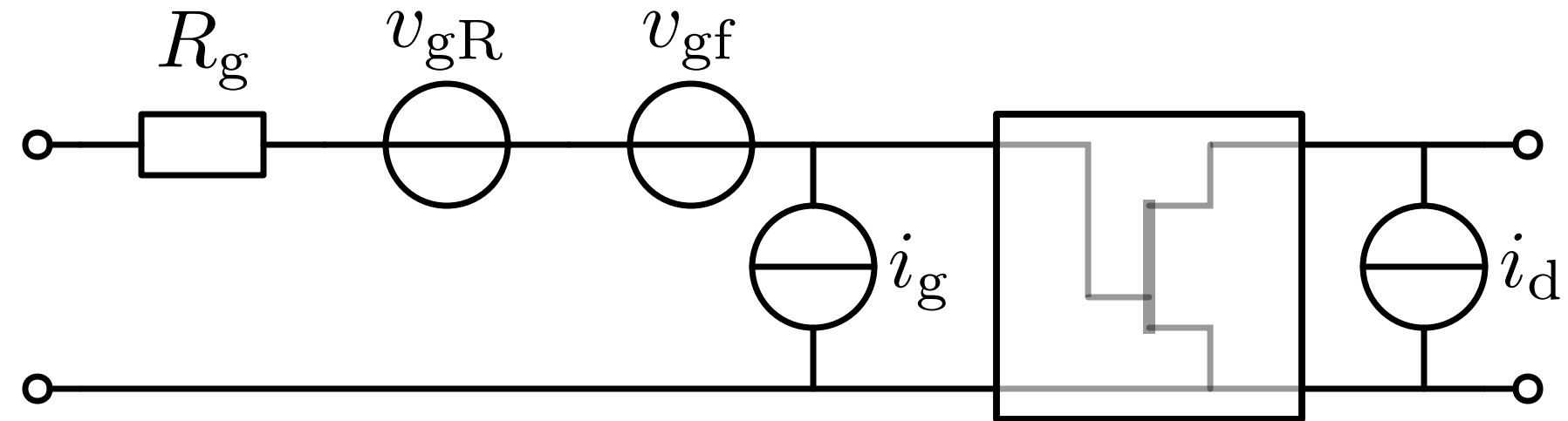


# MOS Noise Model



$R_g$ : gate (series) resistance

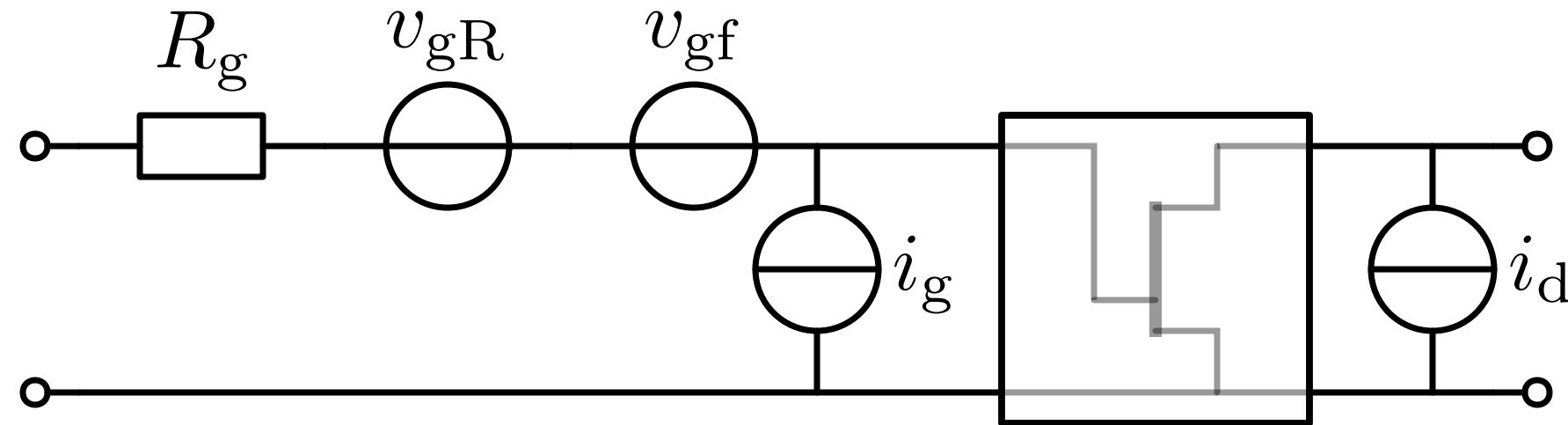
# MOS Noise Model



$R_g$ : gate (series) resistance

$v_{gR}$ : noise voltage gate (series) resistance:  $S_{v_{gR}} = 4kTR_g \text{ V}^2/\text{Hz}$

# MOS Noise Model

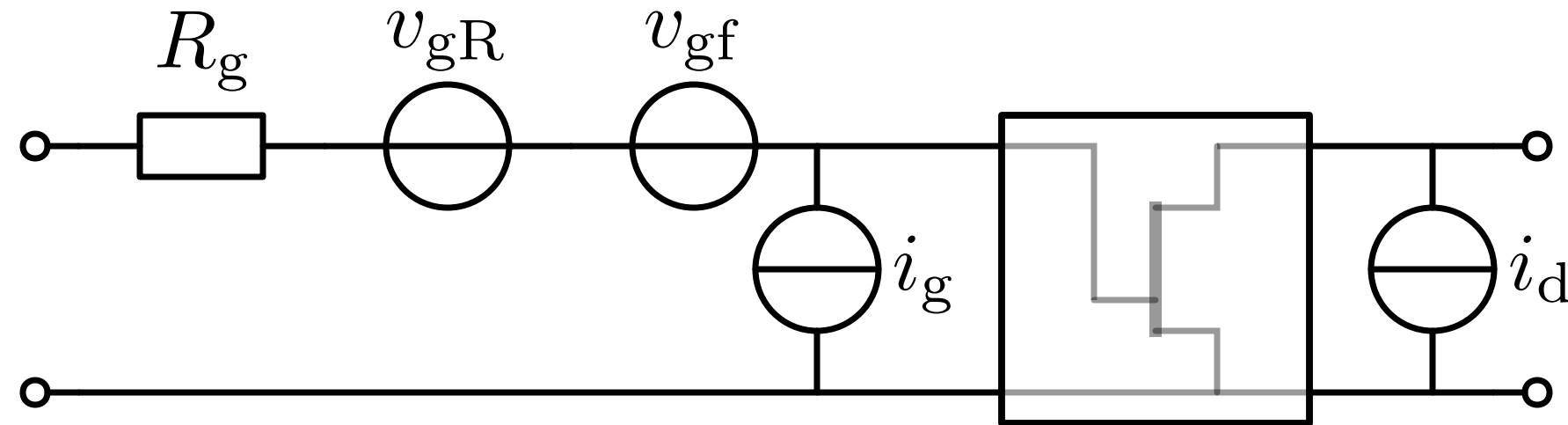


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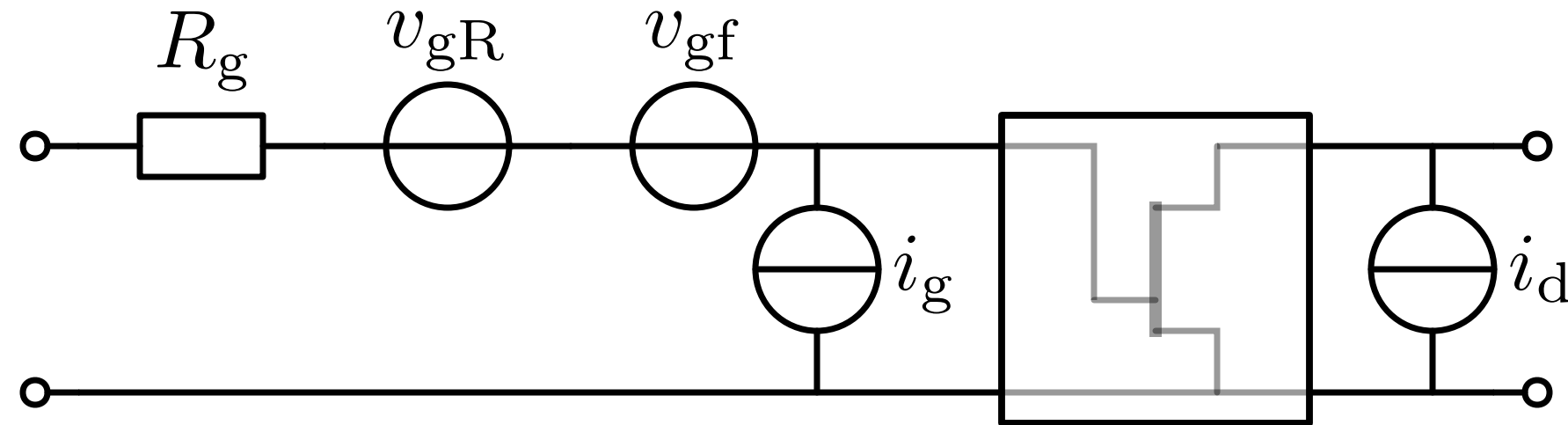
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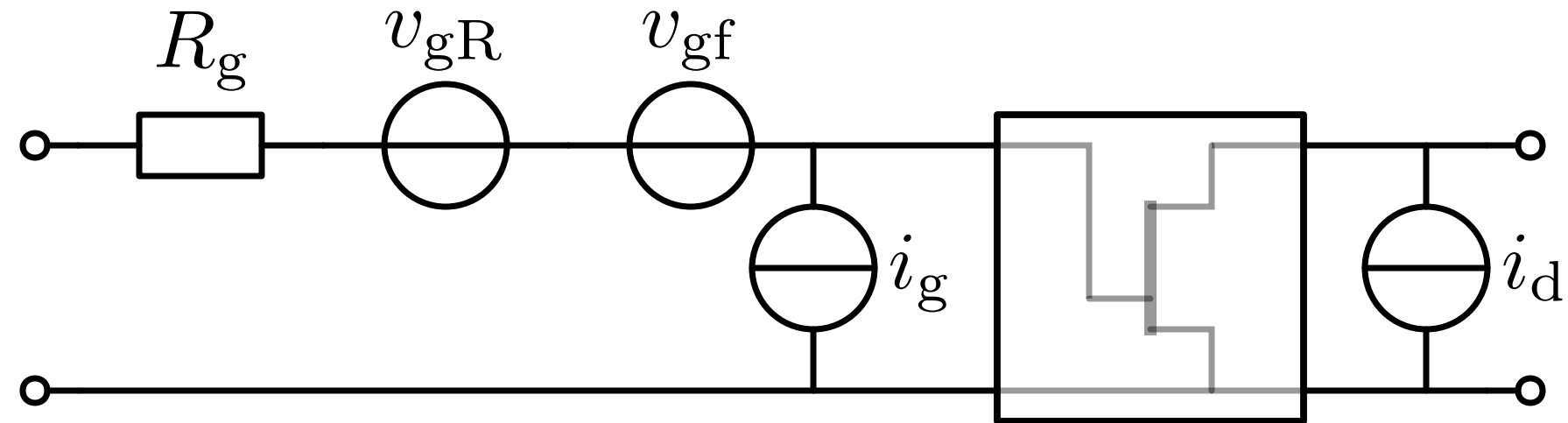
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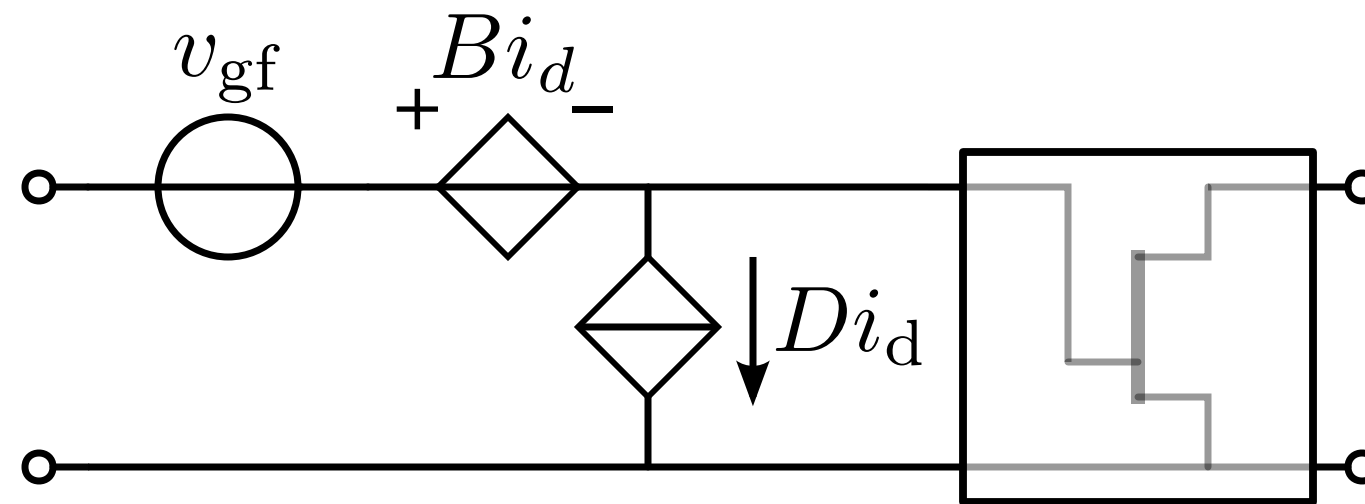
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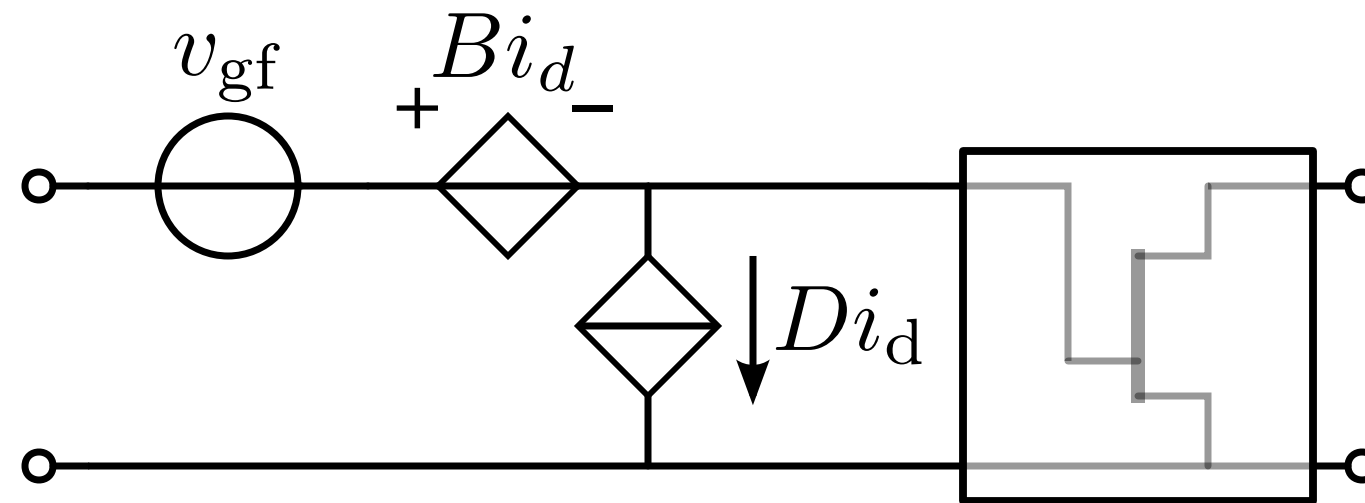
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# MOS Noise Transformations-1

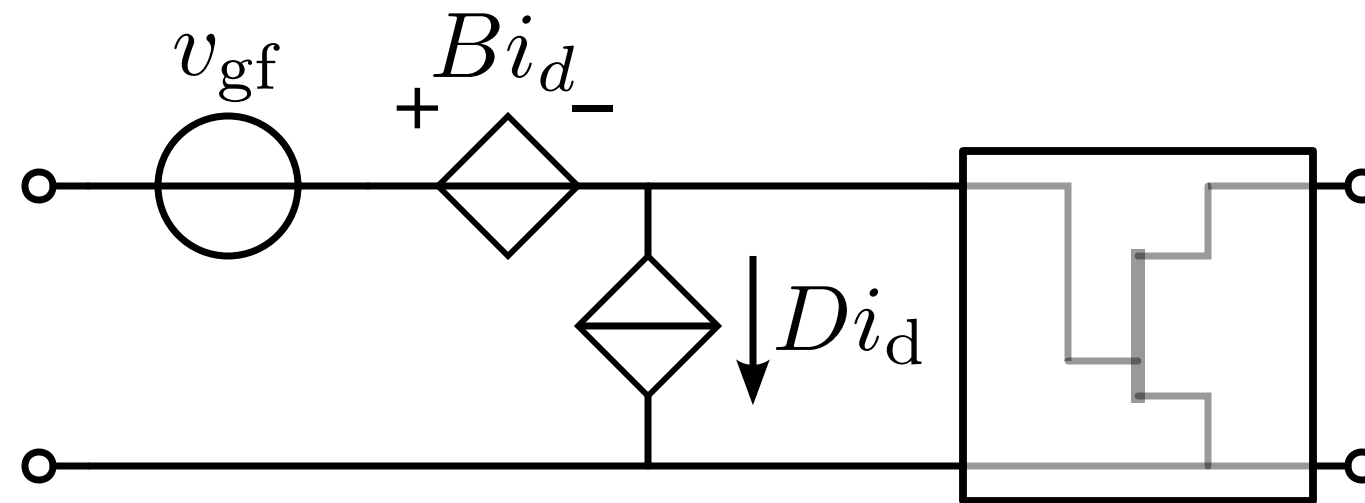


# MOS Noise Transformations-1



$$B = \frac{1}{j2\pi f c_{dg} - g_m} \approx \frac{1}{g_m}$$

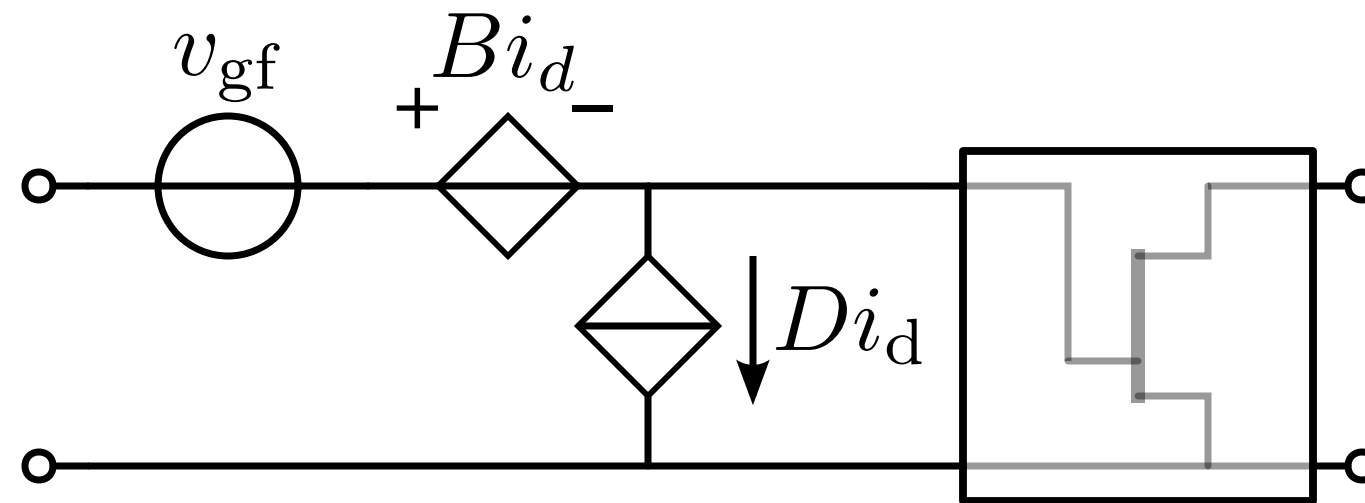
# MOS Noise Transformations-1



$$B = \frac{1}{j2\pi f c_{dg} - g_m} \approx \frac{1}{g_m}$$

$$D = \frac{j2\pi f c_{iss}}{j2\pi f c_{dg} - g_m} \approx \frac{j2\pi f c_{iss}}{g_m}$$

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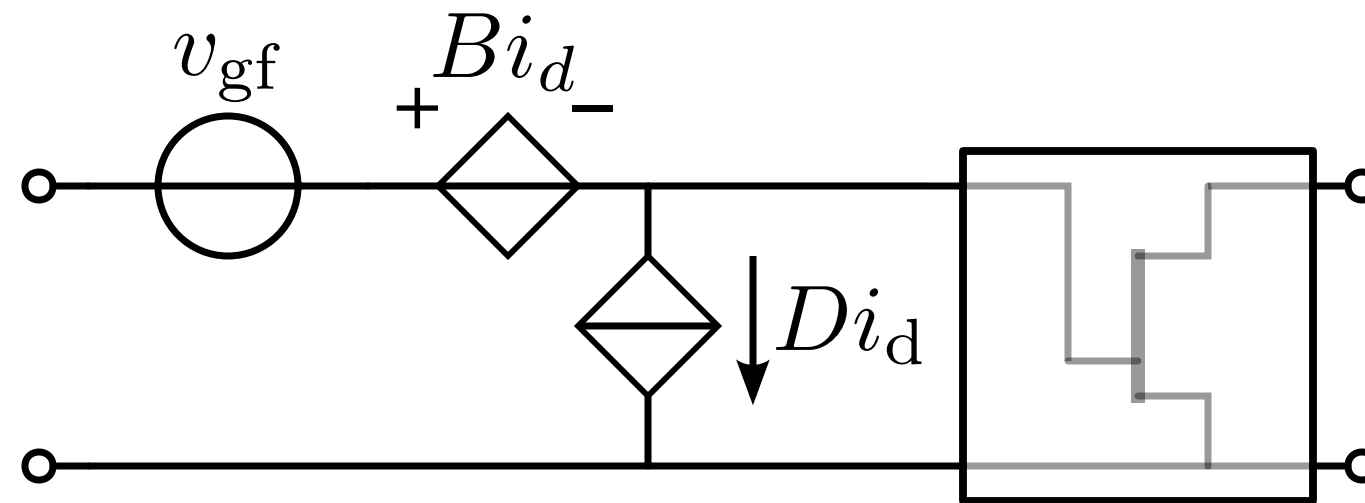


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Negative signs accounted for in the source directions

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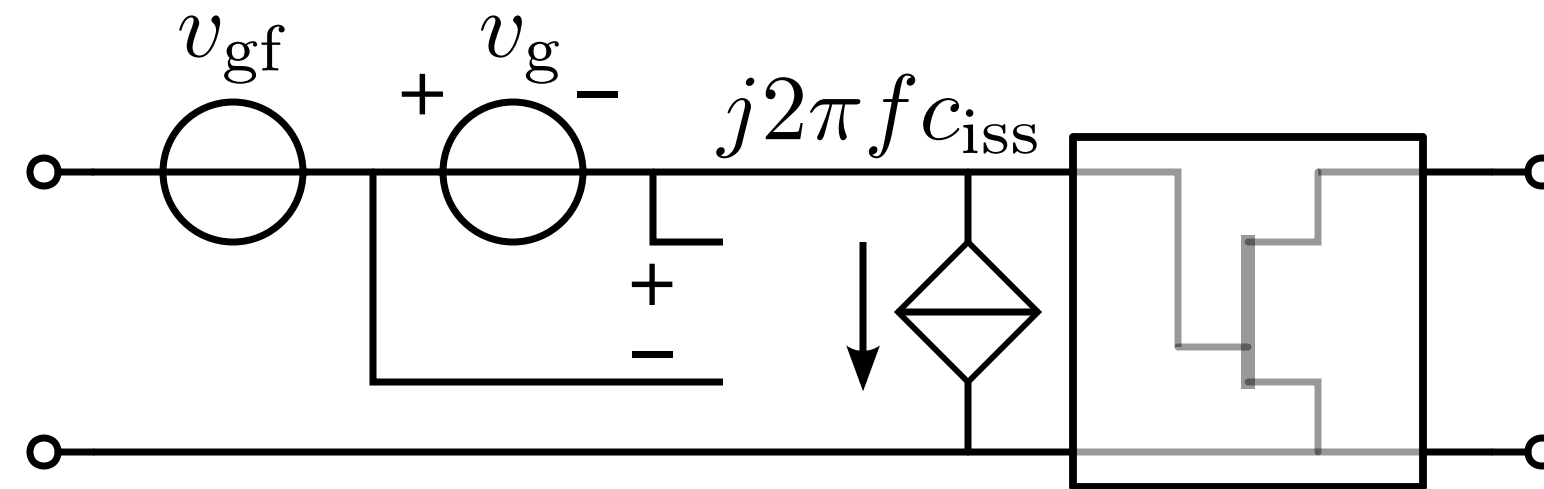


$$B = \frac{1}{j2\pi f c_{dg} - g_m} \approx \frac{1}{g_m}$$

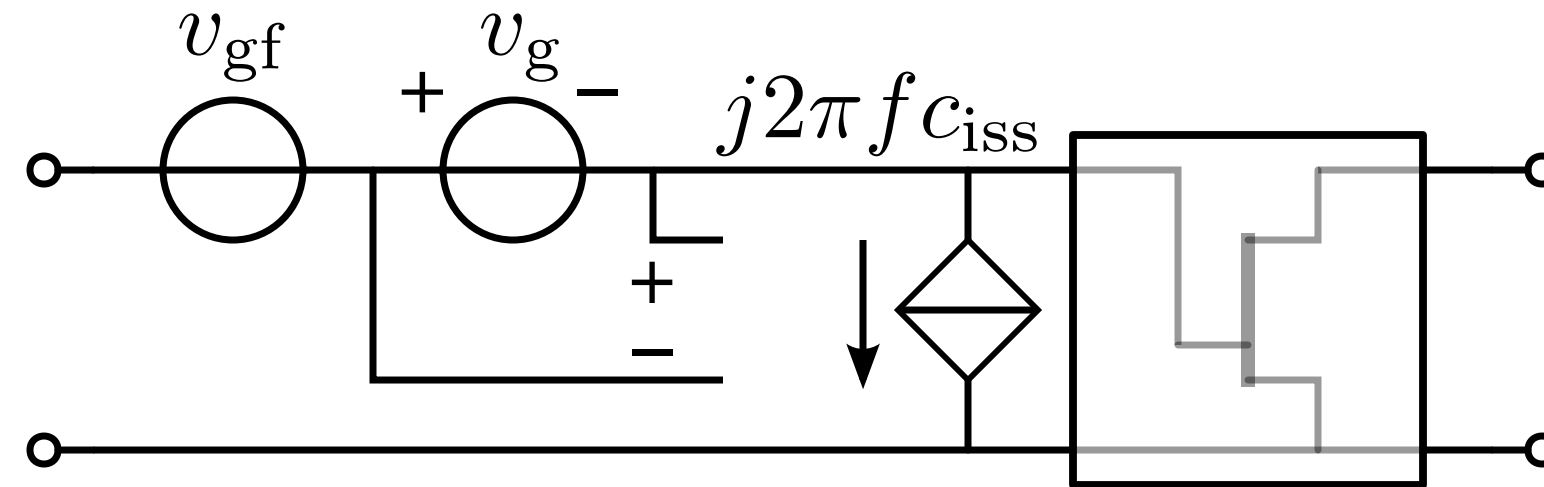
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# MOS Noise Transformations-2

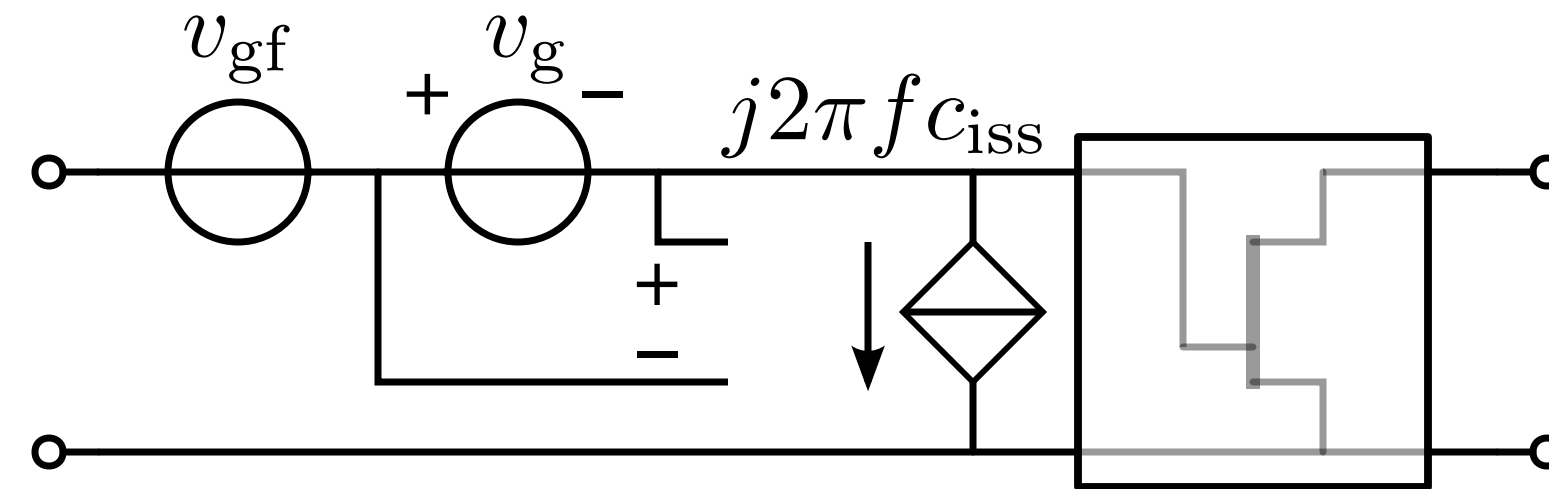


# MOS Noise Transformations-2



$$S_{v_g} = \frac{4kTn\Gamma}{g_m}$$

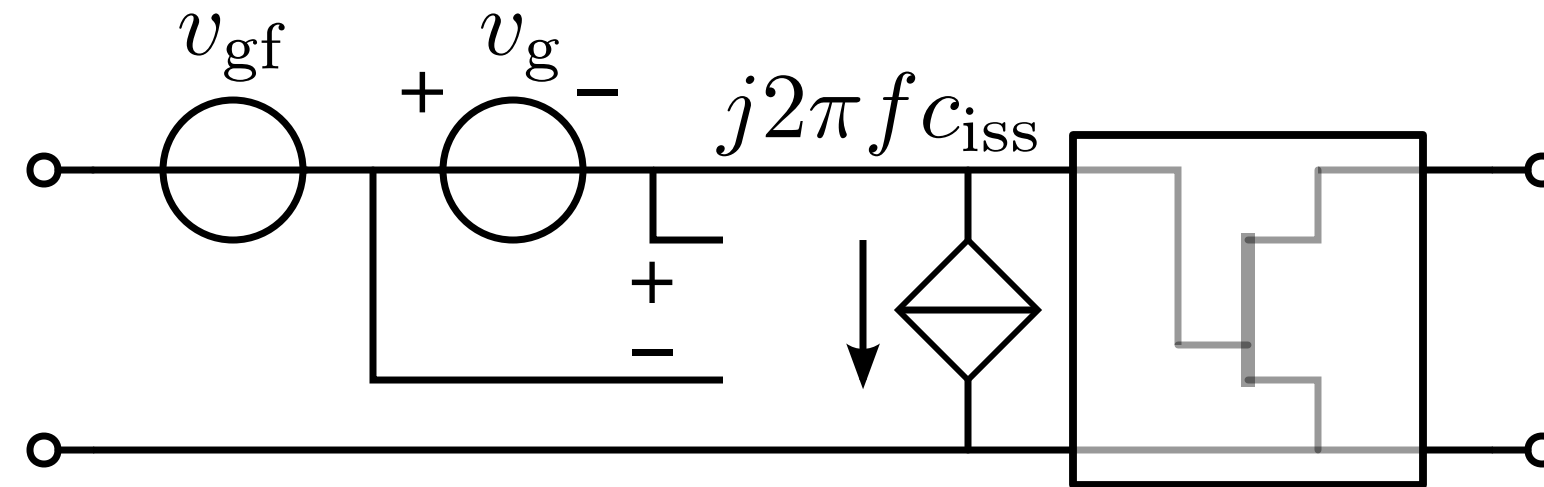
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$$S_{v_g} = \frac{4kTn\Gamma}{g_m}$$

Ignore the overlap capacitances:  
the input capacitance is proportional with the oxide capacitance:

# MOS Noise Transformations-2

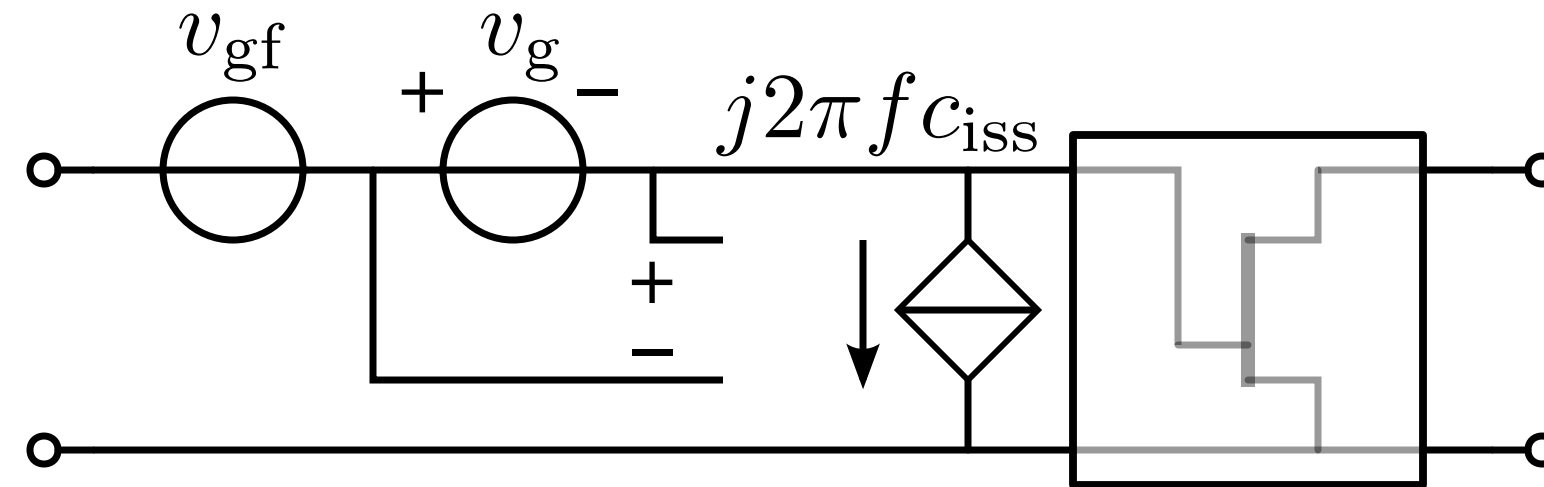


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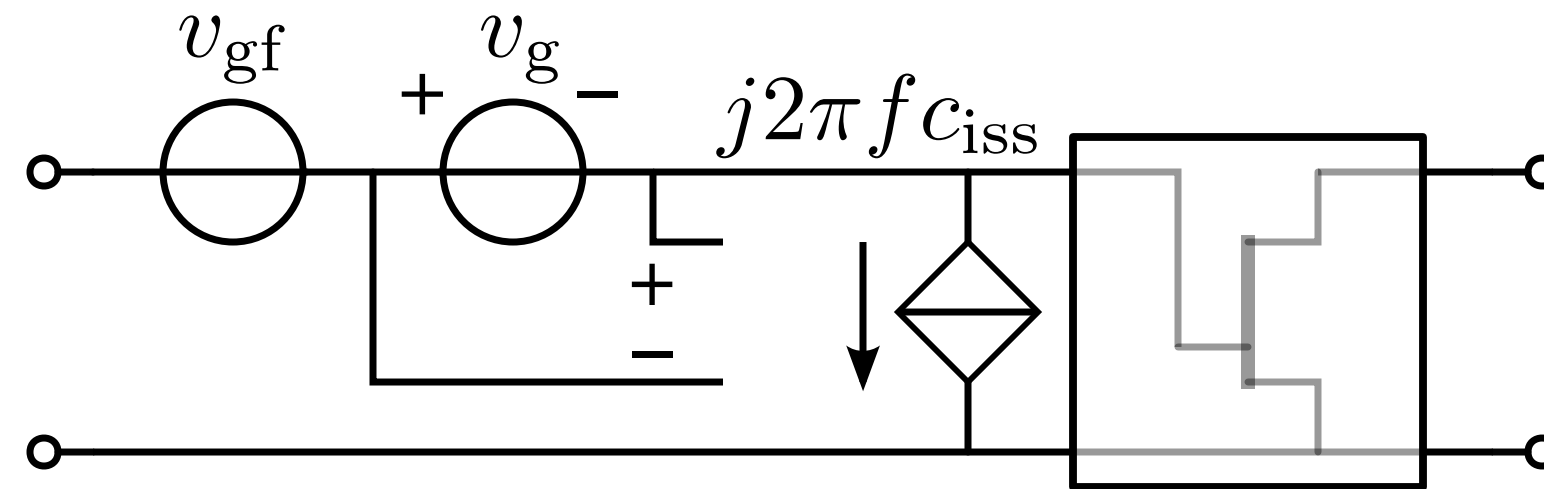
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$\chi$ ,  $\Gamma$  and  $K_F$  depend on the inversion level

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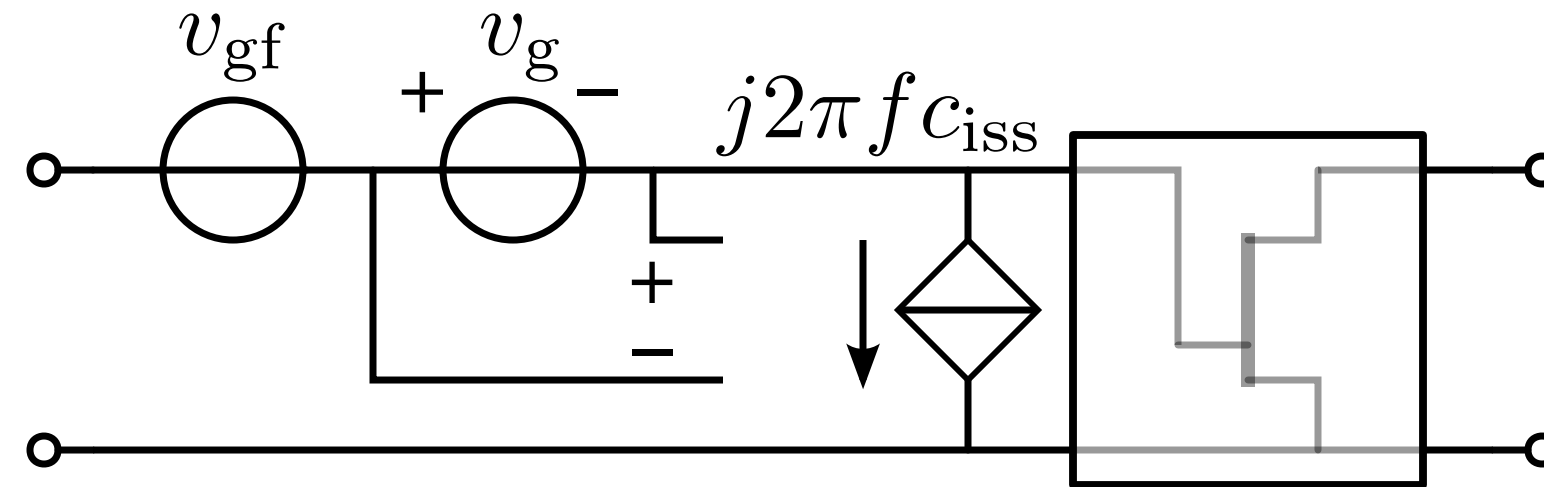
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$\chi = 0.26 \cdots 0.6$  with  $IC = 0 \cdots \infty$  and  $n = 1.35$

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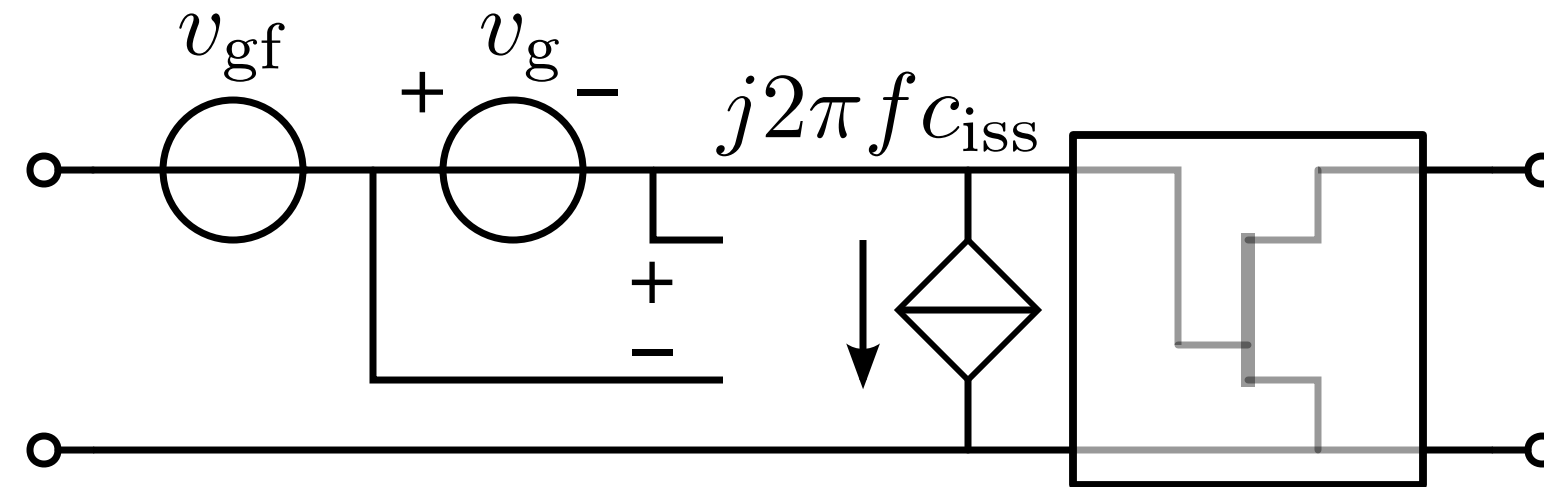
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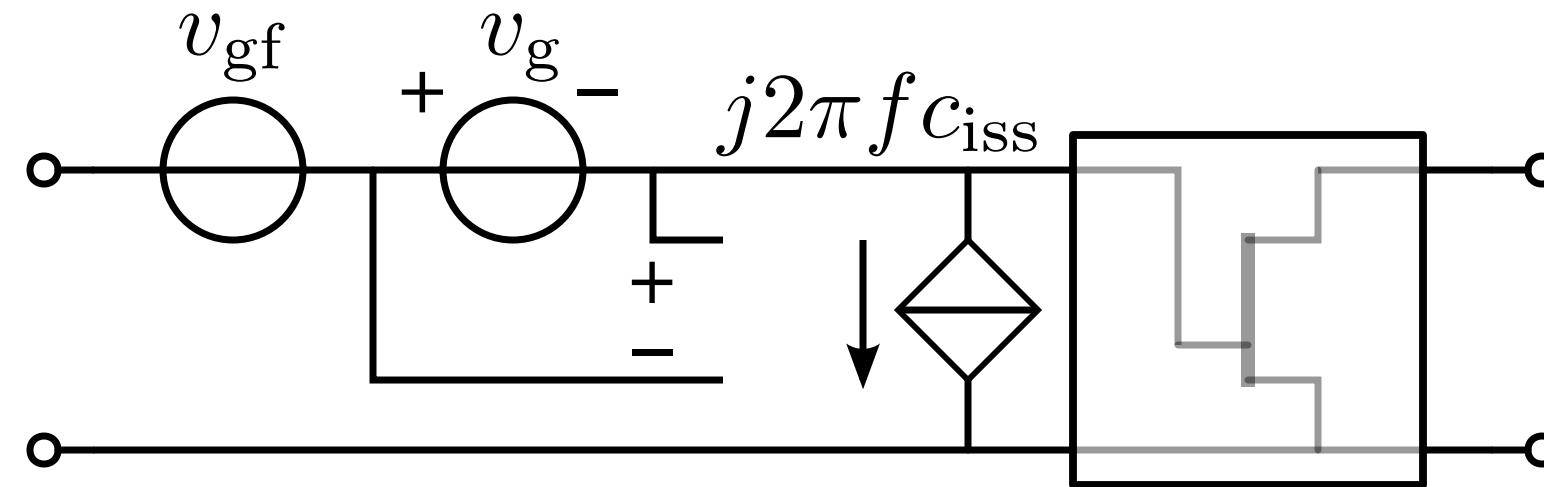
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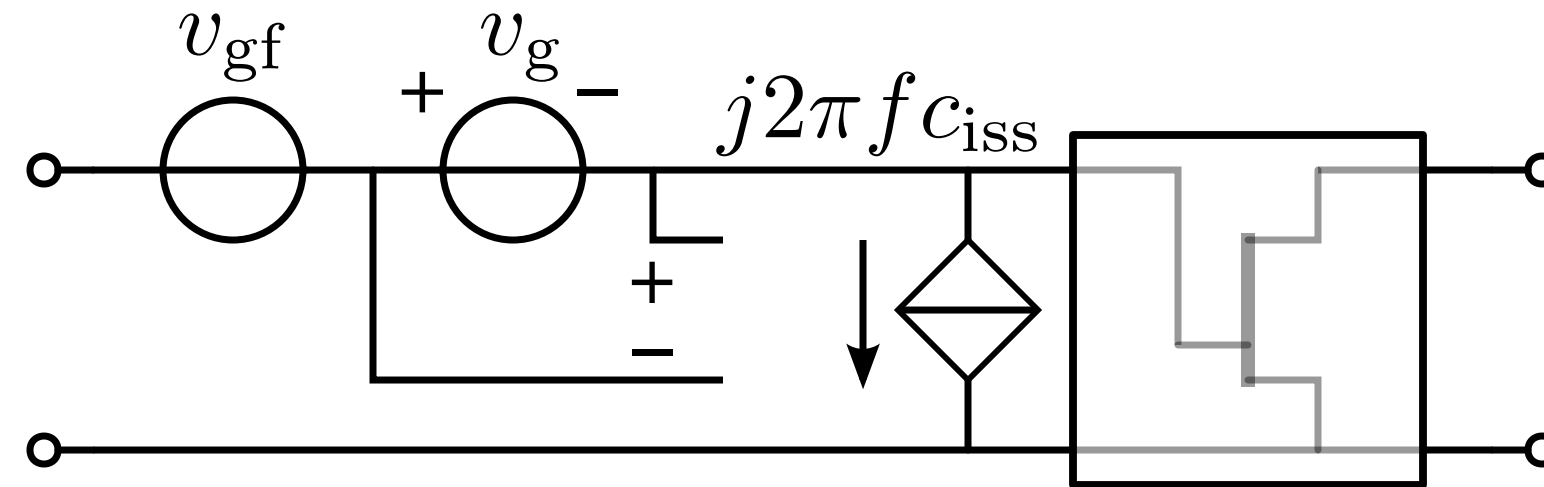
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$S_{v_g}$  and  $S_{v_{gf}}$  are now expressed in the MOS design parameters  $g_m$  and  $c_{iss}$

# MOS Noise Transformations-2



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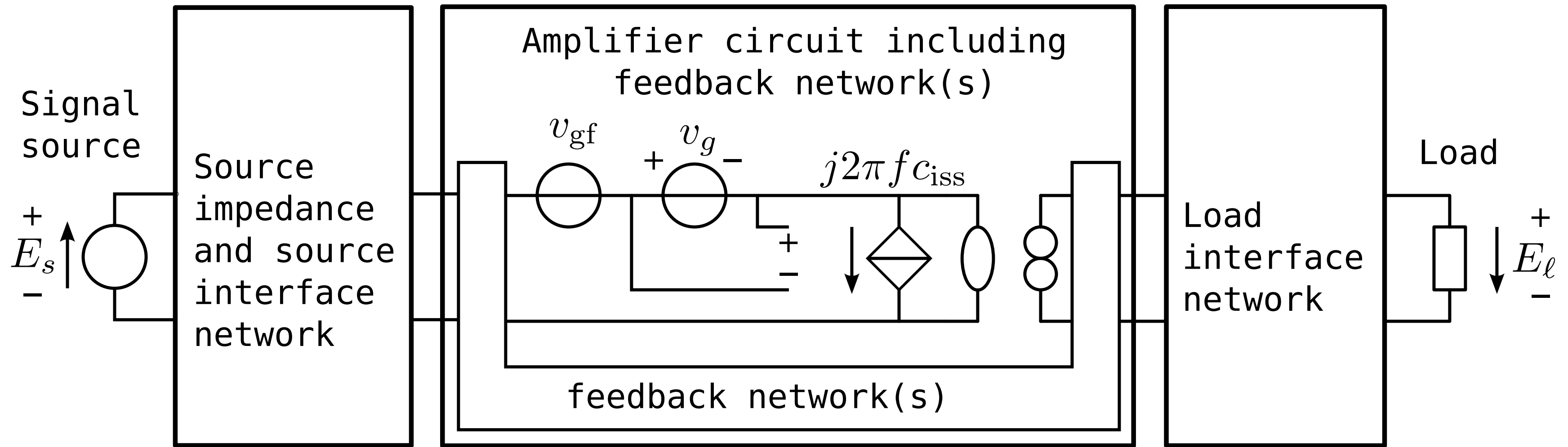
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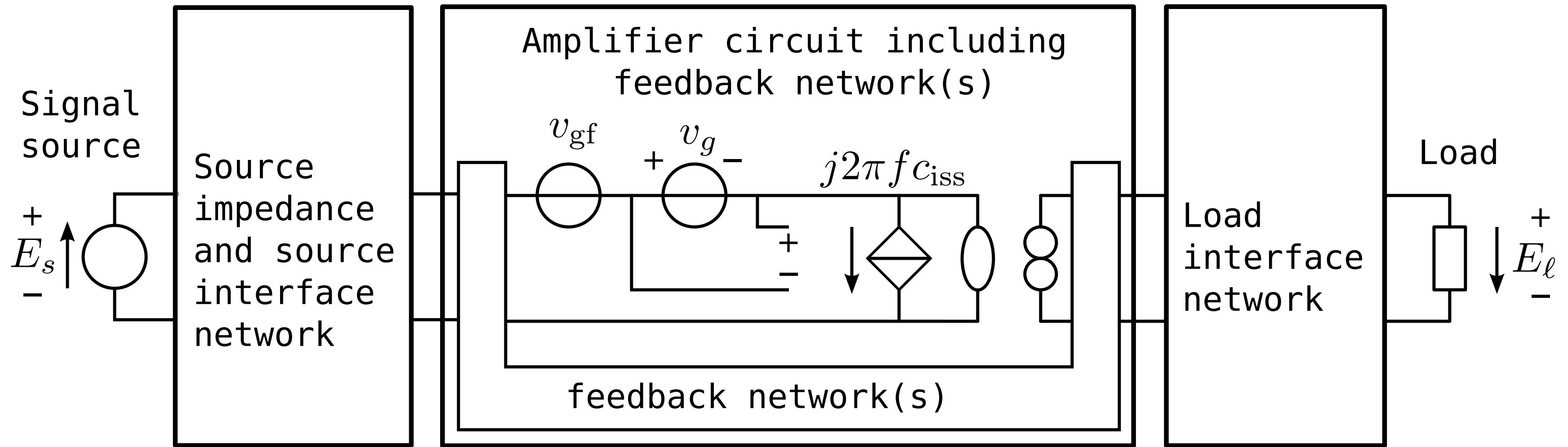
$$K_F = K_{F0} \left(1 + \frac{V_{EFF}}{V_{KF}}\right)^2 \quad V_{KF} = 0.2 \dots 2$$

$S_{v_g}$  and  $S_{v_{gf}}$  are now expressed in the MOS design parameters  $g_m$  and  $c_{iss}$

# Feedback amplifier MOS Noise

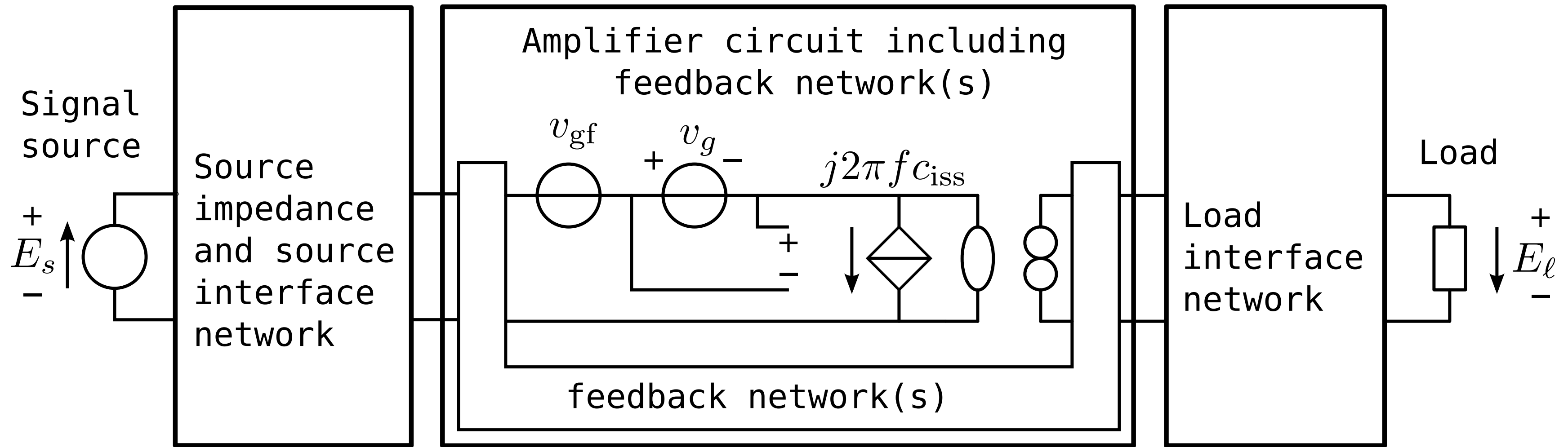


# Feedback amplifier MOS Noise



$$S_{v_g} = \frac{4kTn\Gamma}{g_m} \quad \text{V}^2/\text{Hz}$$

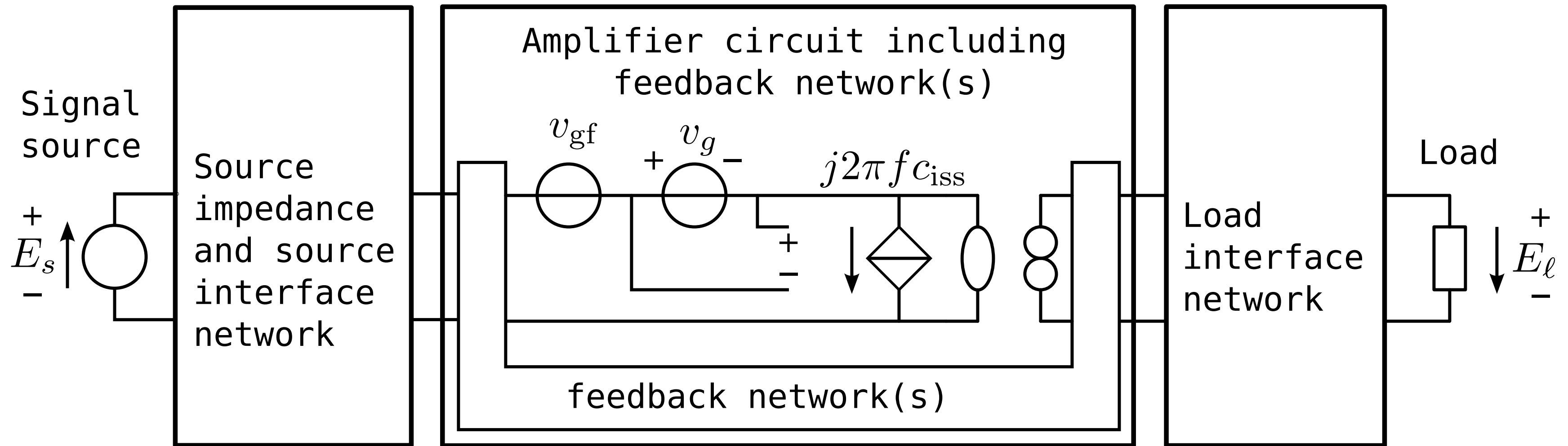
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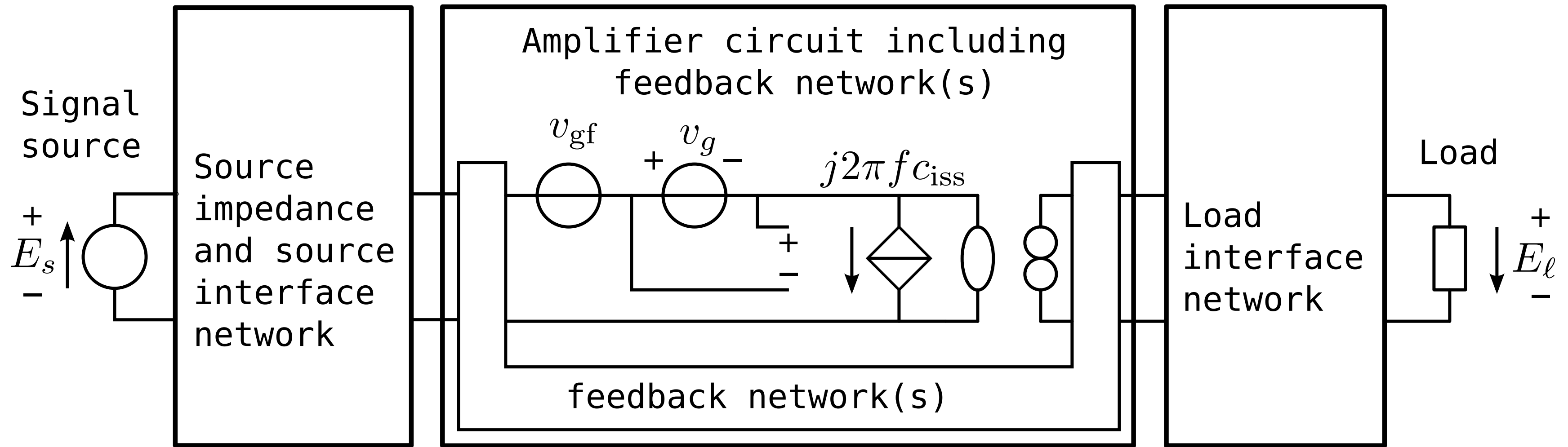


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# Feedback amplifier MOS noise design equation

Unweighted output noise spectrum

$$S_{el} = \frac{\chi K_F}{C_{OX}} \frac{1}{c_{iss} f^{AF}} |H_v|^2 + \frac{4kTn\Gamma}{g_m} |H_v + H_i 2\pi j f c_{iss}|^2 + S_0$$

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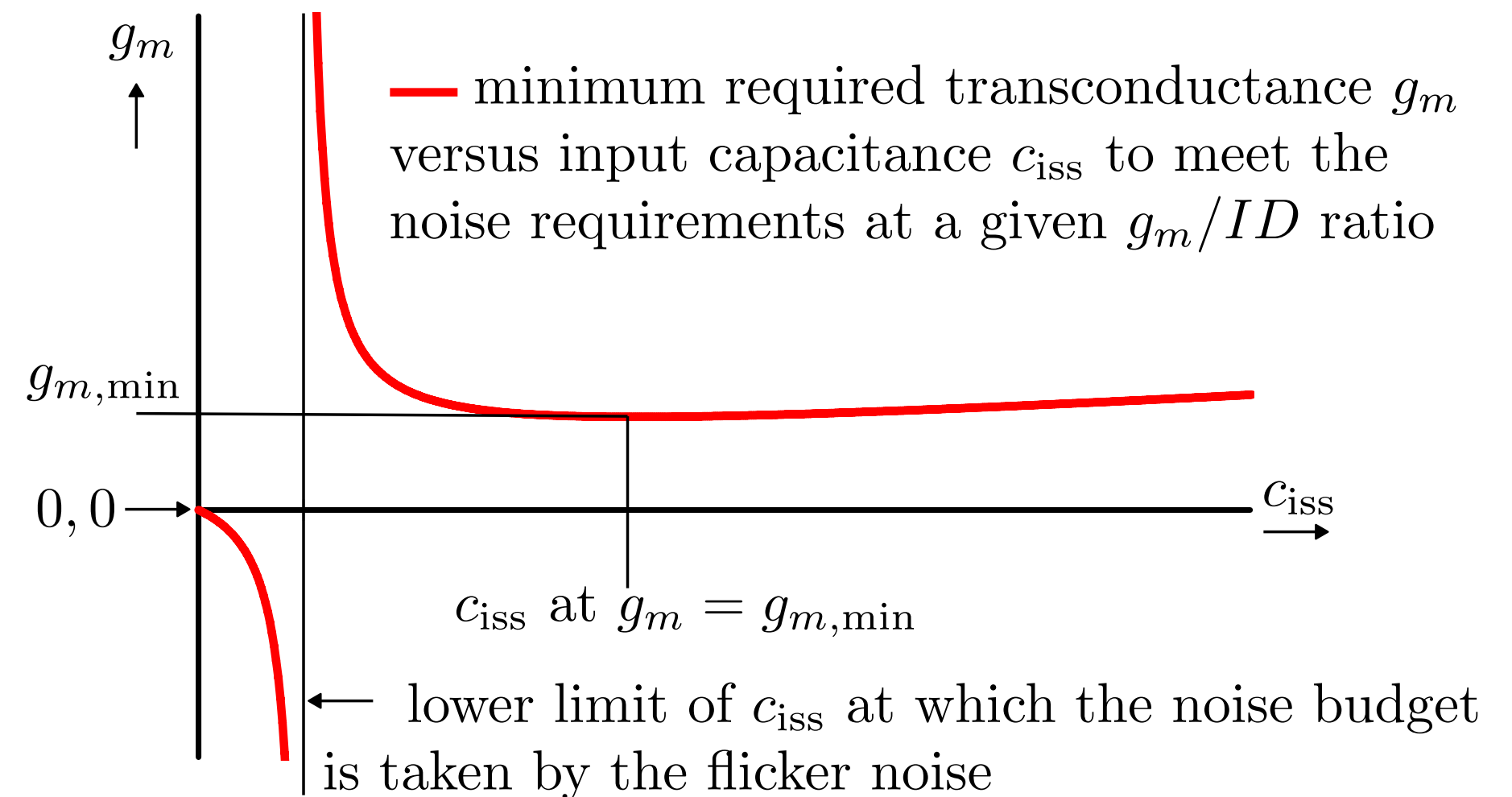
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Lowest noise:

$$e_{\ell}^2 = \frac{\alpha}{c_{issOpt}} + \frac{\beta}{2\pi f_{Tmax} c_{issOpt}} + \frac{\gamma}{2\pi f_{Tmax}} + \frac{\delta c_{issOpt}}{2\pi f_{Tmax}} + \epsilon$$

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If  $\epsilon$  exceeds the requirement for the total squared weighted output noise.

If  $f_T = \frac{g_m}{2\pi c_{iss}}$  is too low:

$$e_{\ell}^2 = \frac{\alpha}{c_{iss}} + \frac{\beta}{2\pi f_T c_{iss}} + \frac{\gamma}{2\pi f_T} + \frac{\delta c_{iss}}{2\pi f_T} + \epsilon \quad c_{issOpt} = \sqrt{\frac{2\pi f_T \alpha + \beta}{\delta}}.$$

Lowest noise:

$$e_{\ell}^2 = \frac{\alpha}{c_{issOpt}} + \frac{\beta}{2\pi f_{Tmax} c_{issOpt}} + \frac{\gamma}{2\pi f_{Tmax}} + \frac{\delta c_{issOpt}}{2\pi f_{Tmax}} + \epsilon$$

Area and current limitations may put extra constraints to the feasibility.

# Feasibility of the noise design

Total squared weighted output noise:

$$e_{\ell}^2 = \alpha \frac{1}{c_{iss}} + \beta \frac{1}{g_m} + \gamma \frac{c_{iss}}{g_m} + \delta \frac{c_{iss}^2}{g_m} + \epsilon$$

MOS contribution to squared weighted output noise:

$$e_{\ell M}^2 = \alpha \frac{1}{c_{iss}} + \beta \frac{1}{g_m} + \gamma \frac{c_{iss}}{g_m} + \delta \frac{c_{iss}^2}{g_m}$$

NOT  
FEASIBLE:

If  $\epsilon$  exceeds the requirement for the total squared weighted output noise.

If  $f_T = \frac{g_m}{2\pi c_{iss}}$  is too low:

$$e_{\ell}^2 = \frac{\alpha}{c_{iss}} + \frac{\beta}{2\pi f_T c_{iss}} + \frac{\gamma}{2\pi f_T} + \frac{\delta c_{iss}}{2\pi f_T} + \epsilon \quad c_{issOpt} = \sqrt{\frac{2\pi f_T \alpha + \beta}{\delta}}.$$

Lowest noise:

$$e_{\ell}^2 = \frac{\alpha}{c_{issOpt}} + \frac{\beta}{2\pi f_{Tmax} c_{issOpt}} + \frac{\gamma}{2\pi f_{Tmax}} + \frac{\delta c_{issOpt}}{2\pi f_{Tmax}} + \epsilon$$

Area and current limitations may put extra constraints to the feasibility.

# From transconductance and capacitance to current and geometry

$$C_{\text{iss}} = \chi C_{\text{OX}} W L + W (C_{\text{GSO}} + C_{\text{GDO}}) + 2 L C_{\text{GBO}}$$

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$$\chi = \frac{2 - x}{3} + \frac{(1 + x)(n - 1)}{3n}$$

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$$\chi = \frac{2 - x}{3} + \frac{(1 + x)(n - 1)}{3n}$$

$$x = \frac{\sqrt{IC + 0.25} + 1.5}{(\sqrt{IC + 0.25} + 0.5)^2}$$

# From transconductance and capacitance to current and geometry

$$c_{\text{iss}} = \chi C_{\text{OX}} W L + W (C_{\text{GSO}} + C_{\text{GDO}}) + 2LC_{\text{GBO}}$$

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$$x = \frac{\sqrt{IC} + 0.25 + 1.5}{(\sqrt{IC} + 0.25 + 0.5)^2}$$

$$I_{\text{DS}} = IC \frac{W}{L} I_0 \quad I_0 \triangleq 2n\mu_0 C_{\text{OX}} V_T^2$$

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$$\frac{g_m}{I_{\text{DS}}} = \frac{1}{nV_T \sqrt{IC \left(1 + \frac{IC}{IC_{\text{crit}}}\right) + 0.5} \sqrt{IC \left(1 + \frac{IC}{IC_{\text{crit}}}\right) + 1}}$$

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Ignore lateral field velocity saturation:

$$IC_{\text{crit}} = (4nV_T\theta)^{-2}$$

# From transconductance and capacitance to current and geometry

$$c_{\text{iss}} = \chi C_{\text{OX}} W L + W (C_{\text{GSO}} + C_{\text{GDO}}) + 2LC_{\text{GBO}}$$

$$c_{\text{iss}} = aWL + bW + cL$$

$$\chi = \frac{2-x}{3} + \frac{(1+x)(n-1)}{3n}$$

$$g_m = d \frac{W}{L}$$

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$$a = \chi C_{\text{OX}}$$

$$b = C_{\text{GSO}} + C_{\text{GDO}}$$

$$c = 2C_{\text{GBO}}$$

$$d = \frac{2\mu_0 C_{\text{OX}} IC}{\sqrt{IC \left(1 + \frac{IC}{IC_{\text{crit}}}\right) + 0.5} \sqrt{IC \left(1 + \frac{IC}{IC_{\text{crit}}}\right) + 1}}$$

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$$W = \frac{cd + bg_m}{2ad} \left( \sqrt{1 + \frac{4adg_m c_{\text{iss}}}{(cd + bg_m)^2}} - 1 \right) \approx \sqrt{\frac{g_m c_{\text{iss}}}{ad}}$$

$$L = \frac{cd + bg_m}{2ag_m} \left( \sqrt{1 + \frac{4adg_m c_{\text{iss}}}{(cd + bg_m)^2}} - 1 \right) \approx \sqrt{\frac{d c_{\text{iss}}}{ag_m}}$$

$$I_{\text{DS}} = \frac{1}{g_m / I_{\text{DS}}} g_m$$

# From transconductance and capacitance to current and geometry

$$c_{\text{iss}} = \chi C_{\text{OX}} W L + W (C_{\text{GSO}} + C_{\text{GDO}}) + 2 L C_{\text{GBO}}$$

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Ignore lateral field velocity saturation:

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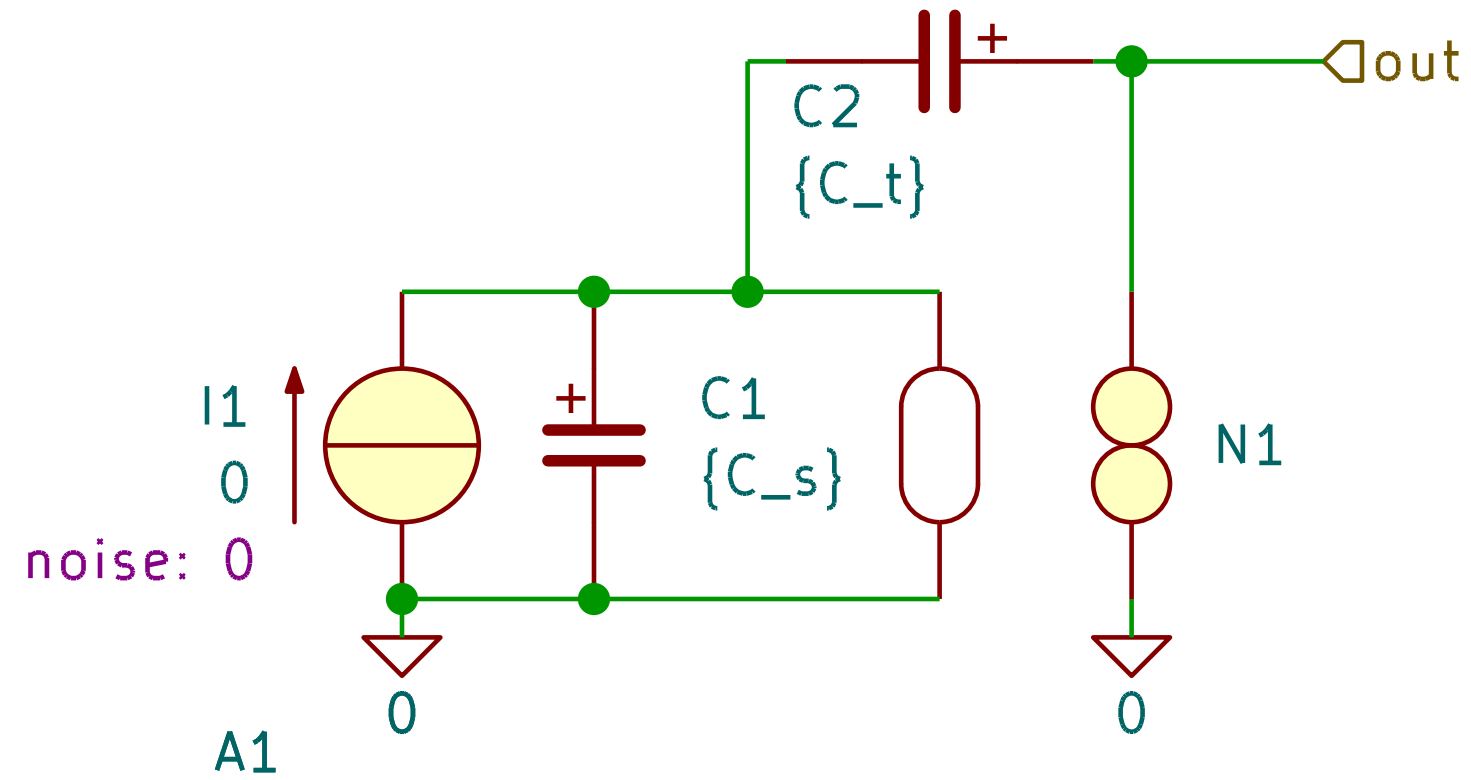
$$I_{\text{DS}} = \frac{1}{g_m / I_{\text{DS}}} g_m$$

# Example

Transimpedance integrator with capacitive source

# Example

## Transimpedance integrator with capacitive source



A1

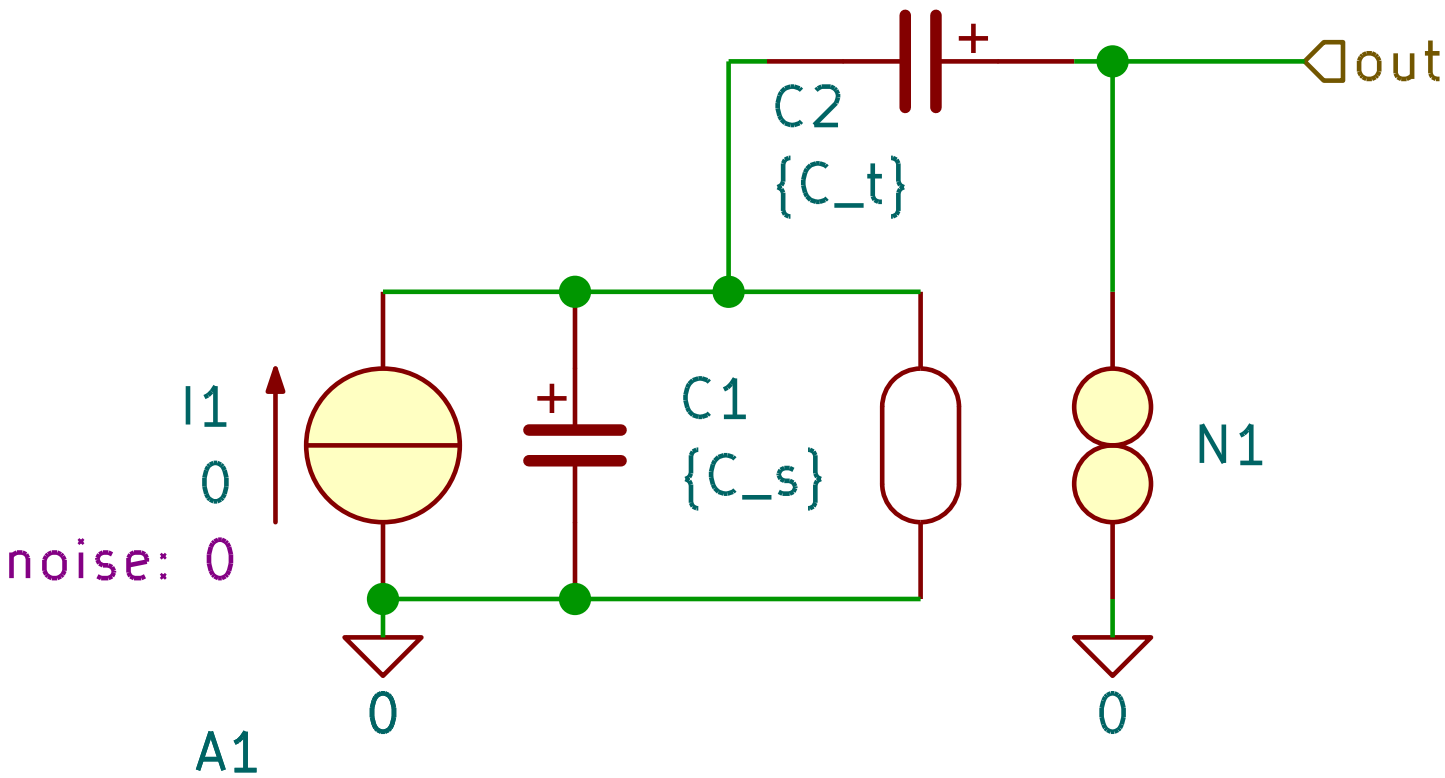
.detector V\_out

A2

.param C\_s=1p C\_t=0.2p IG=0

# Example

## Transimpedance integrator with capacitive source



.detector V\_out

A2

.param C\_s=1p C\_t=0.2p IG=0

Coefficients of the symbolic noise equation  
(determined with SLiCAP):

term coefficient

$$\frac{1}{c_{iss}} \quad \alpha = \int_{f_{min}}^{f_{max}} \frac{K_F \chi f^{-A_F} (C_s + C_t)^2}{C_O X C_t^2} df$$

$$\frac{1}{g_m} \quad \beta = \int_{f_{min}}^{f_{max}} \frac{4\Gamma T k n (C_s + C_t)^2}{C_t^2} df$$

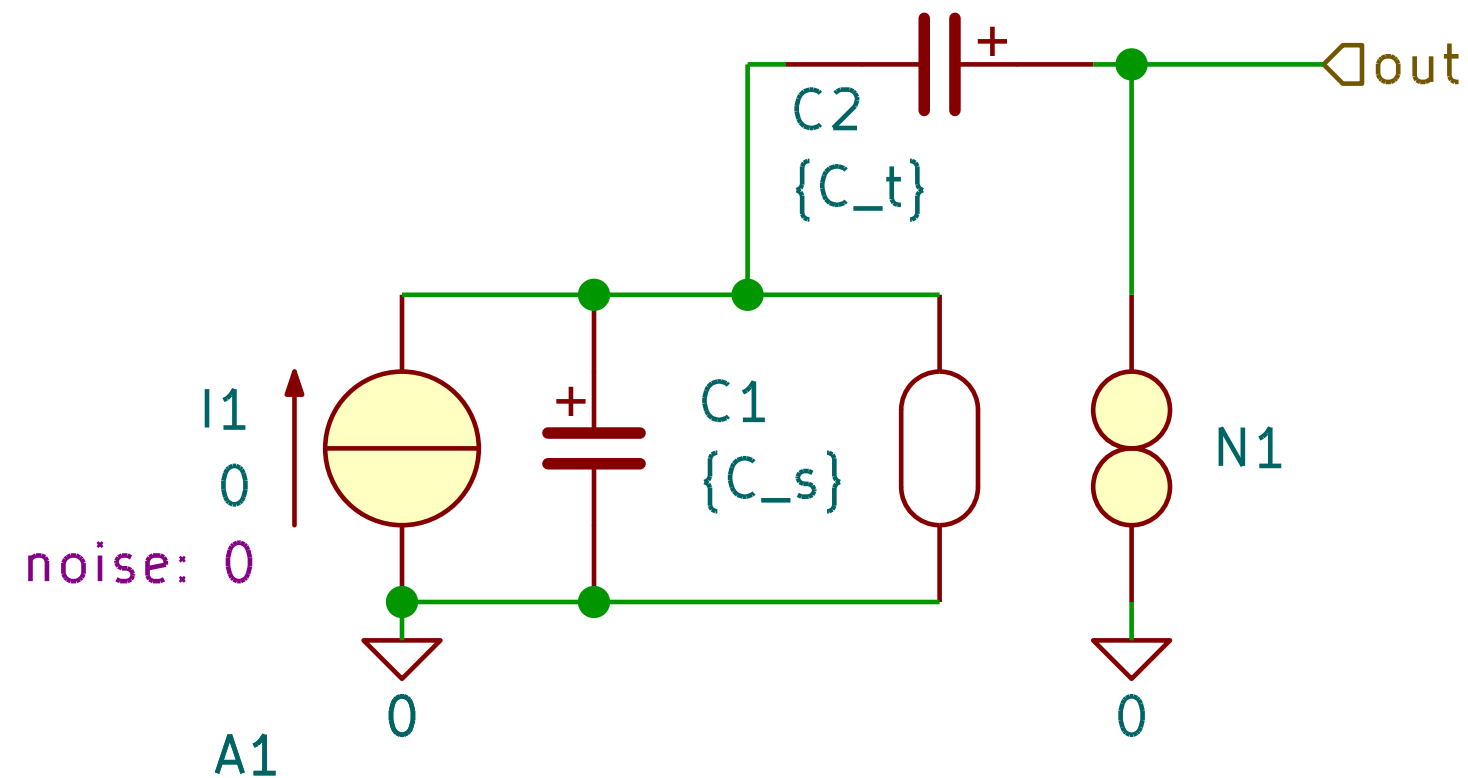
$$\frac{c_{iss}}{g_m} \quad \gamma = \int_{f_{min}}^{f_{max}} \frac{8\Gamma T k n (C_s + C_t)}{C_t^2} df$$

$$\frac{c_{iss}^2}{g_m} \quad \delta = \int_{f_{min}}^{f_{max}} \frac{4\Gamma T k n}{C_t^2} df$$

$$1 \quad \epsilon = 0$$

# Example

## Transimpedance integrator with capacitive source



If we ignore flicker noise:

$$C_{issOpt} = \sqrt{\frac{\beta}{\delta}} = C_s + C_t = 1.2 \text{ pF}$$

$$v_{n_{out}}^2 = \frac{16kTn\Gamma}{g_m} \left( \frac{C_s + C_t}{C_t} \right)^2 (f_{max} - f_{min})$$

Coefficients of the symbolic noise equation (determined with SLiCAP):

term coefficient

$$\frac{1}{C_{iss}} \quad \alpha = \int_{f_{min}}^{f_{max}} \frac{K_F \chi f^{-A_F} (C_s + C_t)^2}{C_O X C_t^2} df$$

$$\frac{1}{g_m} \quad \beta = \int_{f_{min}}^{f_{max}} \frac{4\Gamma T k n (C_s + C_t)^2}{C_t^2} df$$

$$\frac{C_{iss}}{g_m} \quad \gamma = \int_{f_{min}}^{f_{max}} \frac{8\Gamma T k n (C_s + C_t)}{C_t^2} df$$

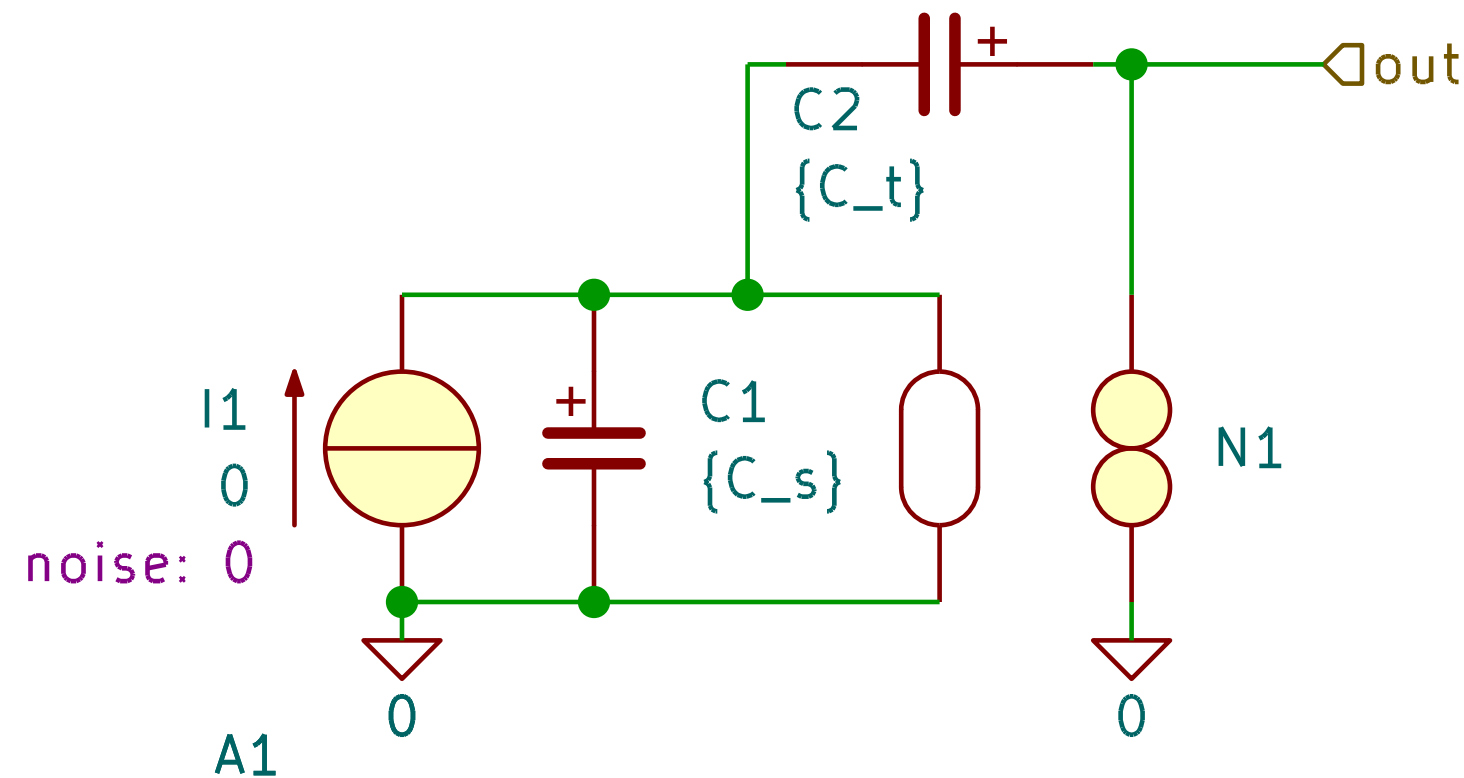
$$\frac{C_{iss}^2}{g_m} \quad \delta = \int_{f_{min}}^{f_{max}} \frac{4\Gamma T k n}{C_t^2} df$$

$$1 \quad \epsilon = 0$$



# Example

## Transimpedance integrator with capacitive source



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$$\frac{1}{C_{iss}} \quad \alpha = \int_{f_{min}}^{f_{max}} \frac{K_F \chi f^{-A_F} (C_s + C_t)^2}{C_{OX} C_t^2} df$$

$$\frac{1}{g_m} \quad \beta = \int_{f_{min}}^{f_{max}} \frac{4\Gamma T k n (C_s + C_t)^2}{C_t^2} df$$

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$$1 \quad \epsilon = 0$$

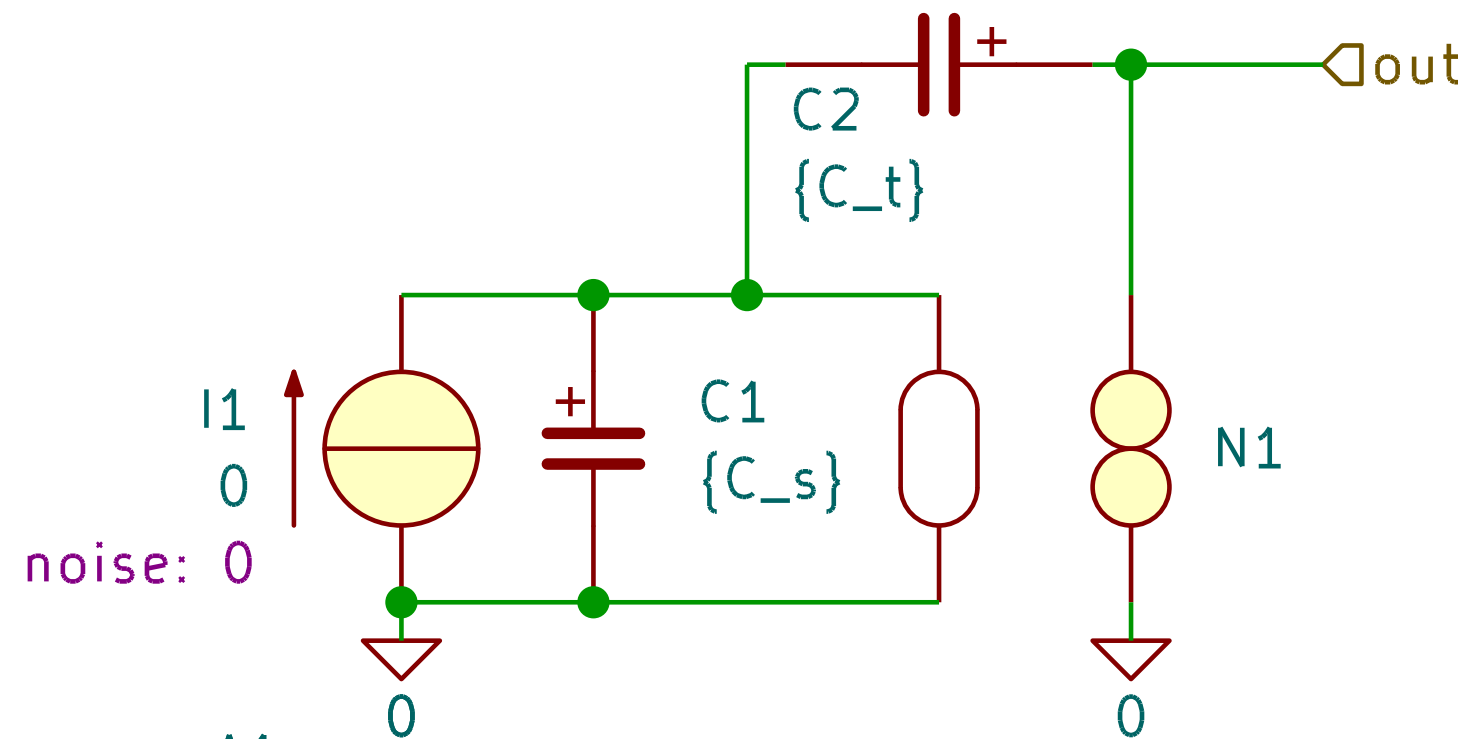


# SLiCAP design automation

# SLiCAP design automation

1. Select CMOS process and fit EKV parameters to BSIM

# SLiCAP design automation



noise: 0

A1

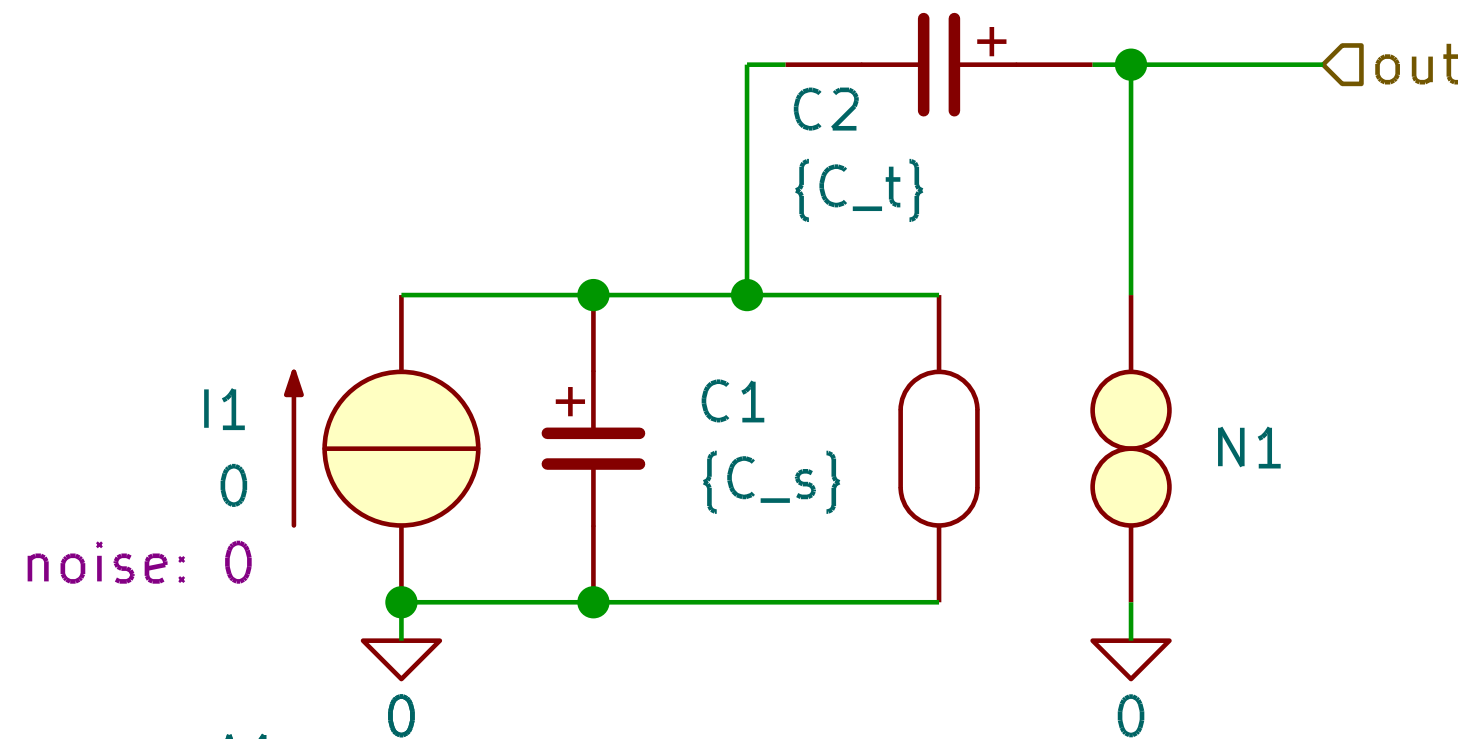
.detector V\_out

A2

.param C\_s=1p C\_t=0.2p IG=0

1. Select CMOS process and fit EKV parameters to BSIM
2. Create KiCAD amplifier circuit with nullor as controller

# SLiCAP design automation



# A1

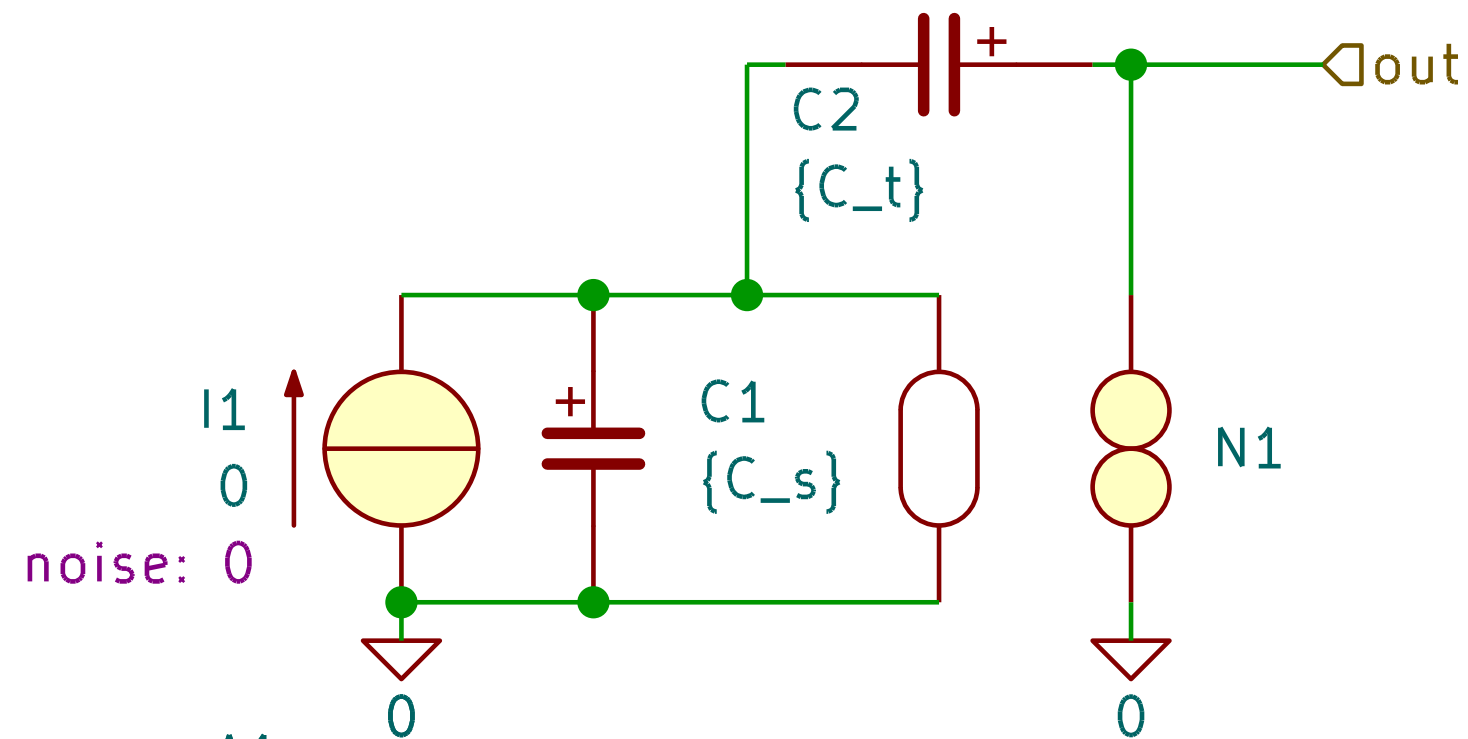
```
.detector V_out
```

## A2

```
.param C_s=1p C_t=0.2p IG=0
```

1. Select CMOS process and fit EKV parameters to BSIM
2. Create KiCAD amplifier circuit with nullor as controller
3. Define noise requirements (frequency range and budgets)

# SLiCAP design automation



A1

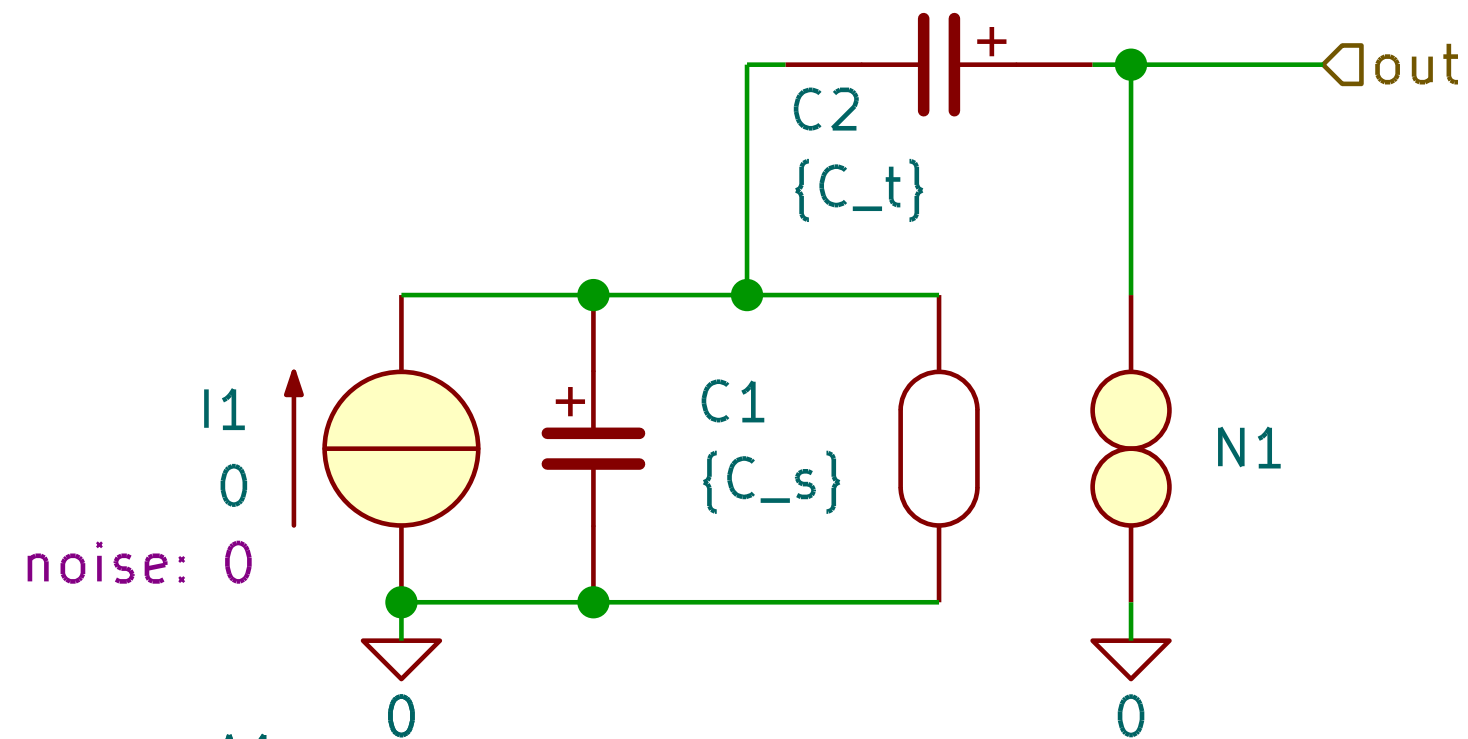
.detector V\_out

A2

.param C\_s=1p C\_t=0.2p IG=0

1. Select CMOS process and fit EKV parameters to BSIM
2. Create KiCAD amplifier circuit with nullor as controller
3. Define noise requirements (frequency range and budgets)
4. Define technology requirements  
(channel type, minimum and maximum geometry)

# SLiCAP design automation



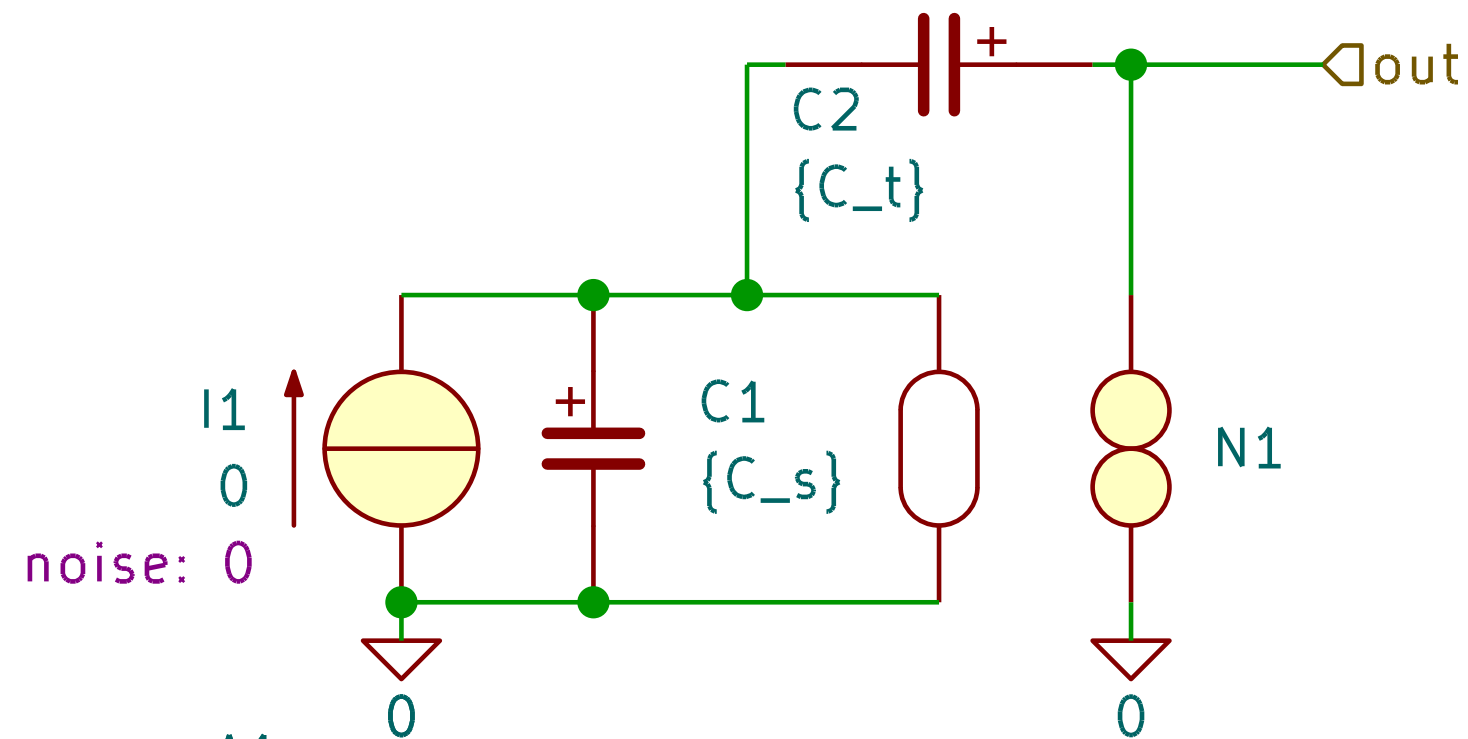
.detector V\_out

A2

.param C\_s=1p C\_t=0.2p IG=0

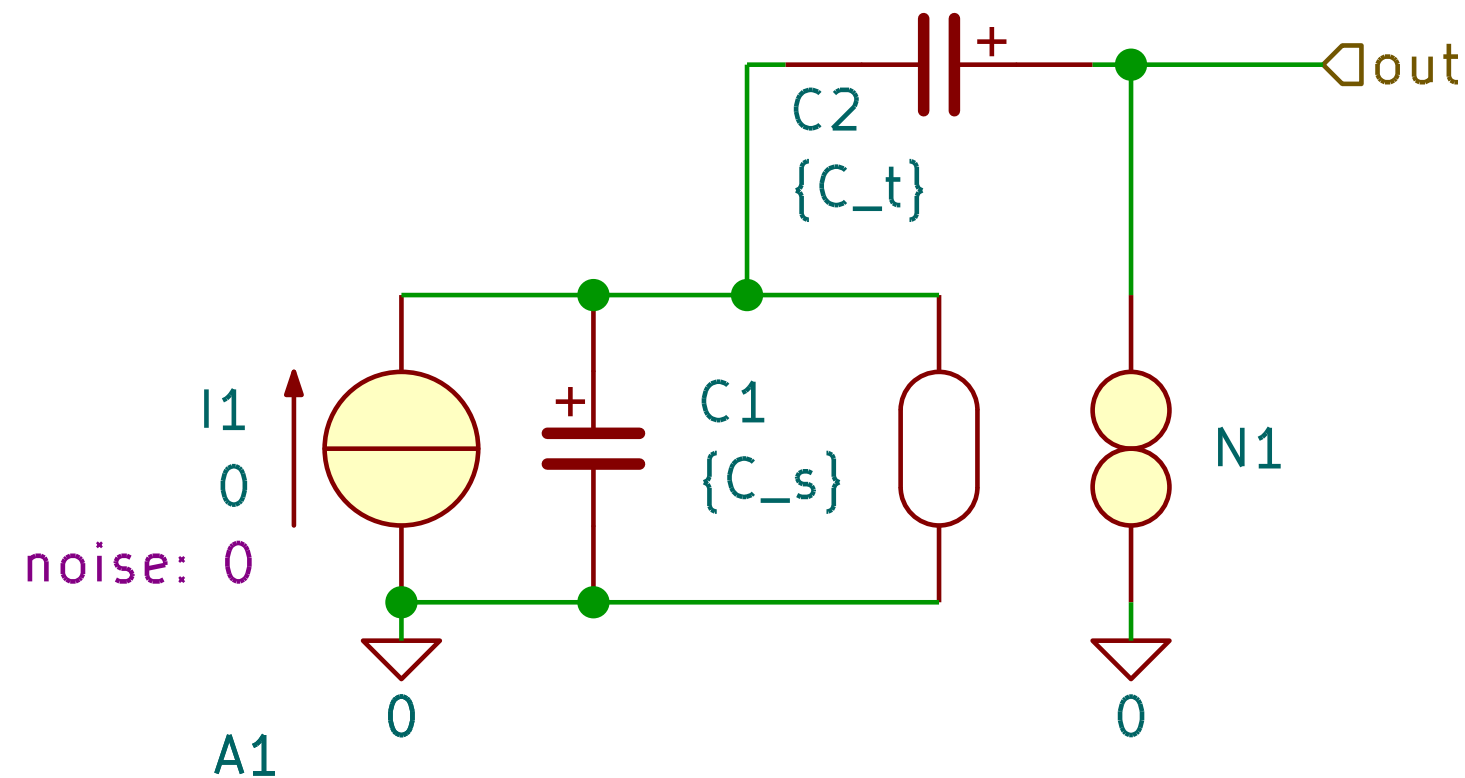
1. Select CMOS process and fit EKV parameters to BSIM
2. Create KiCAD amplifier circuit with nullor as controller
3. Define noise requirements (frequency range and budgets)
4. Define technology requirements  
(channel type, minimum and maximum geometry)
5. Define circuit requirements  
(inversion coefficient or gm/ID ratio, and current budget)

# SLiCAP design automation



1. Select CMOS process and fit EKV parameters to BSIM
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3. Define noise requirements (frequency range and budgets)
4. Define technology requirements  
(channel type, minimum and maximum geometry)
5. Define circuit requirements  
(inversion coefficient or gm/ID ratio, and current budget)
6. Run the design automation script

# SLiCAP design automation



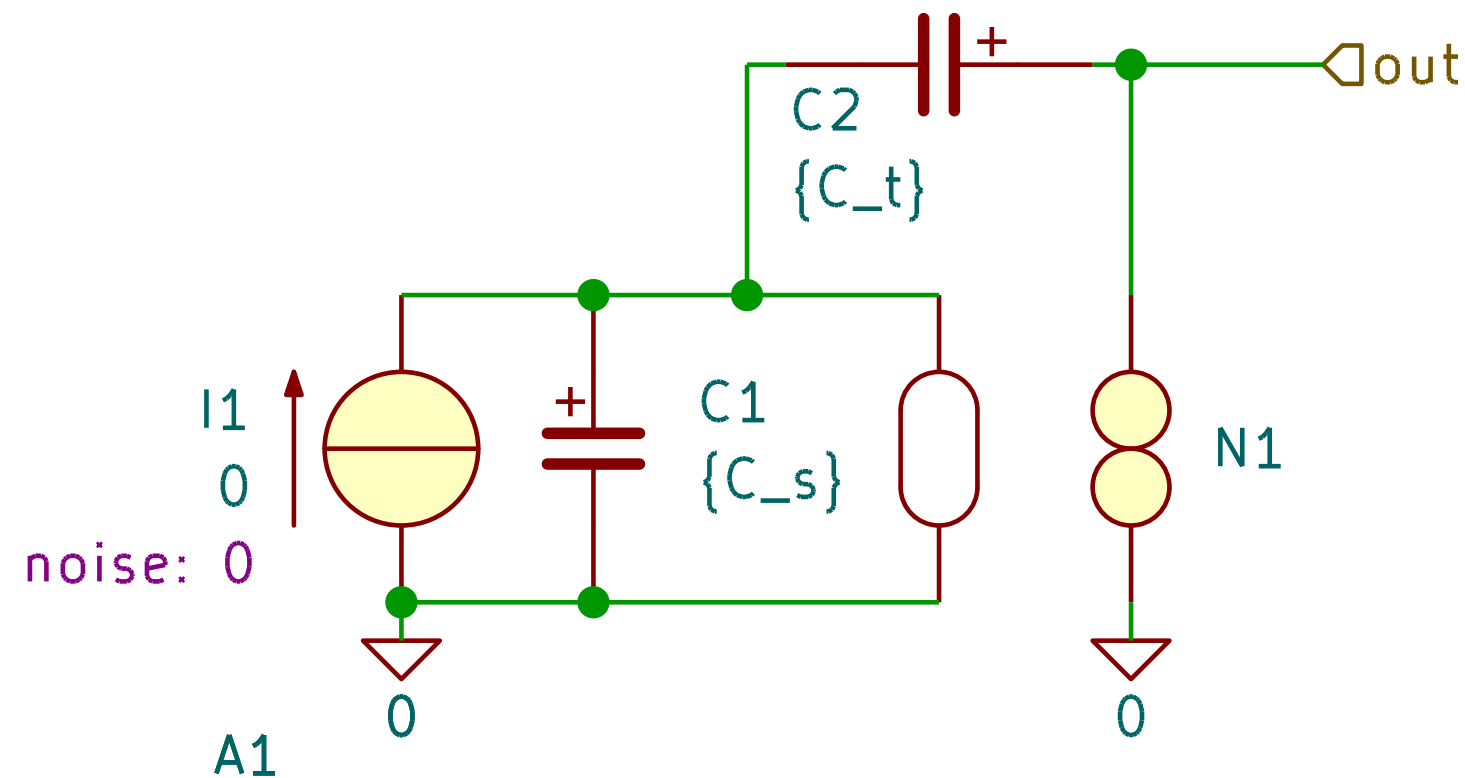
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5. Define circuit requirements  
(inversion coefficient or gm/ID ratio, and current budget)
6. Run the design automation script
7. Select one valid option for design

# SLiCAP design automation



.detector V\_out

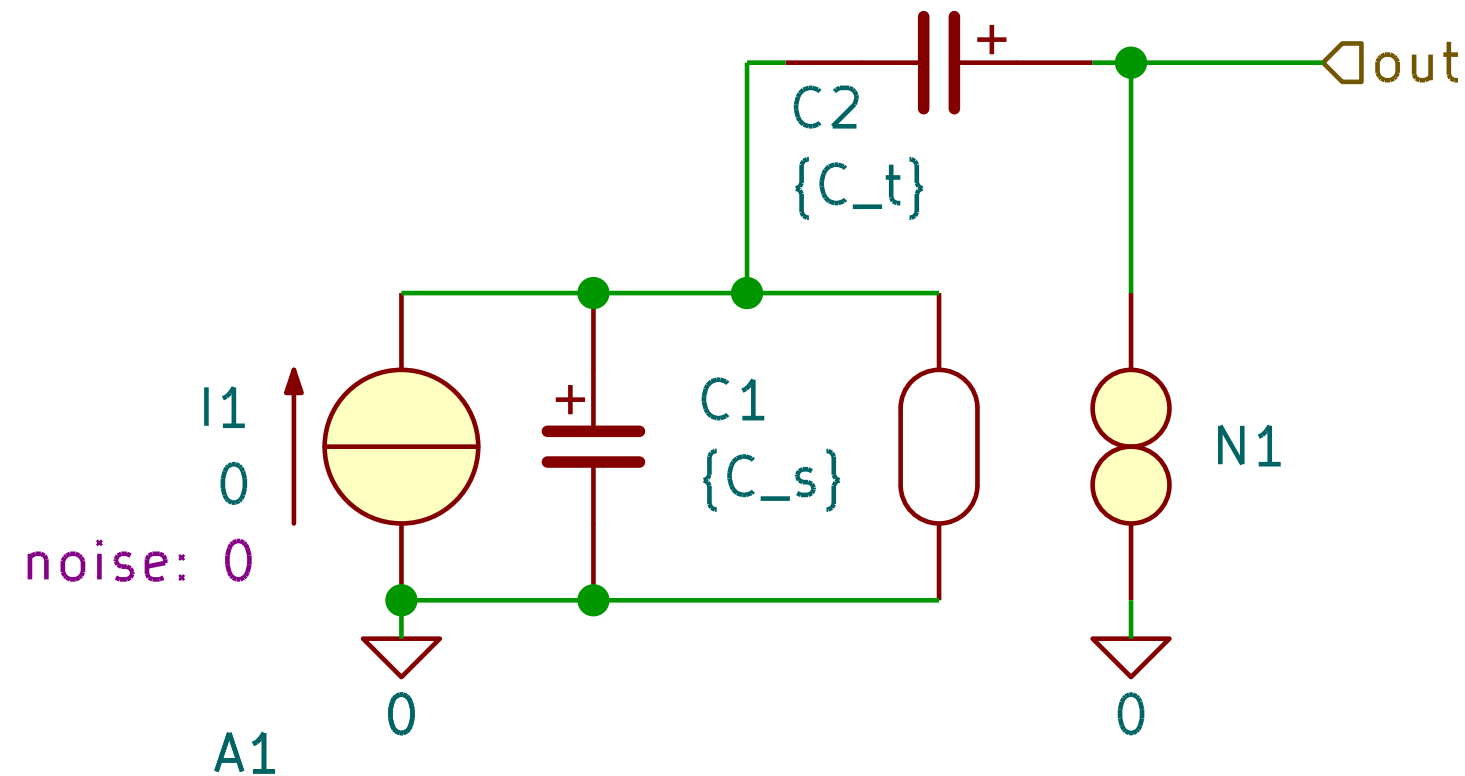
A2

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5. Define circuit requirements  
(inversion coefficient or gm/ID ratio, and current budget)
6. Run the design automation script
7. Select one valid option for design

SLiCAP replaces the nullor with an N-channel or a P-channel noisy nullor and evaluates  $W$ ,  $L$ , and  $I_{DS}$  for six scenarios for the selected inversion coefficient or gm/ID ratio:

# SLiCAP design automation



.detector V\_out

A2

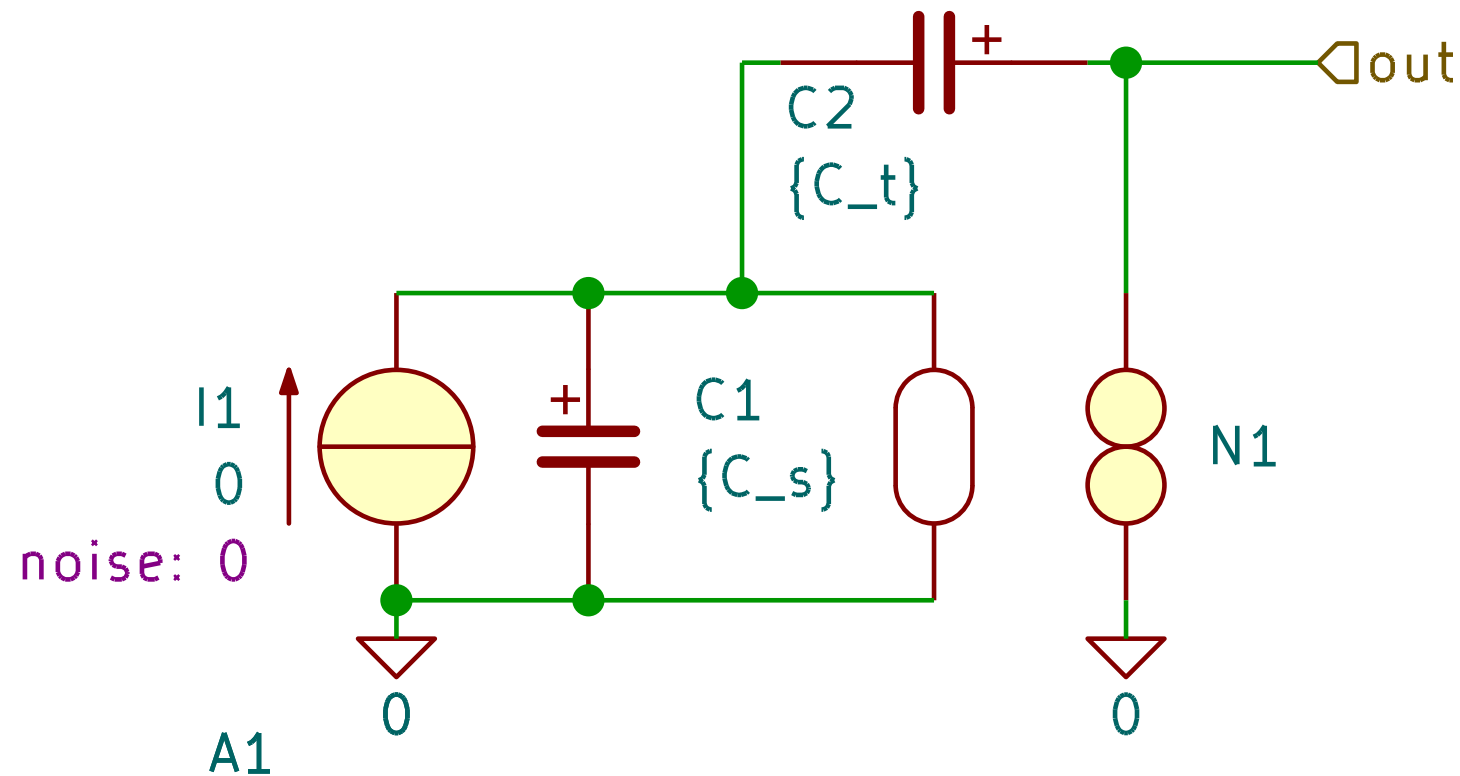
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6. Run the design automation script
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SLiCAP replaces the nullor with an N-channel or a P-channel noisy nullor and evaluates  $W$ ,  $L$ , and  $I_{DS}$  for six scenarios for the selected inversion coefficient or gm/ID ratio:

1. Minimum noise at maximum inversion level

# SLiCAP design automation



.detector V\_out

A2

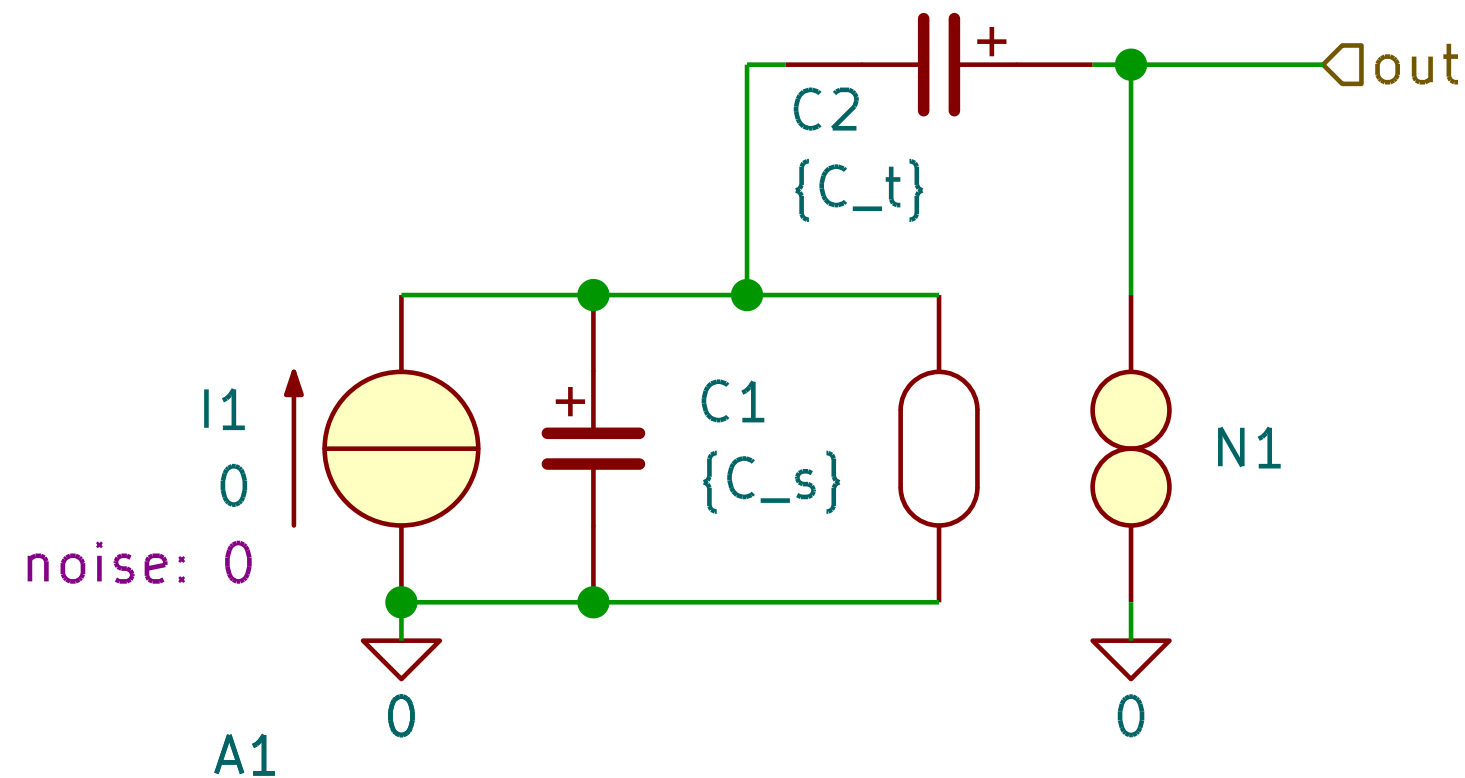
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(channel type, minimum and maximum geometry)
5. Define circuit requirements  
(inversion coefficient or gm/ID ratio, and current budget)
6. Run the design automation script
7. Select one valid option for design

SLiCAP replaces the nullor with an N-channel or a P-channel noisy nullor and evaluates  $W$ ,  $L$ , and  $I_{DS}$  for six scenarios for the selected inversion coefficient or gm/ID ratio:

1. Minimum noise at maximum inversion level
2. Minimum current to meet the noise specification

# SLiCAP design automation

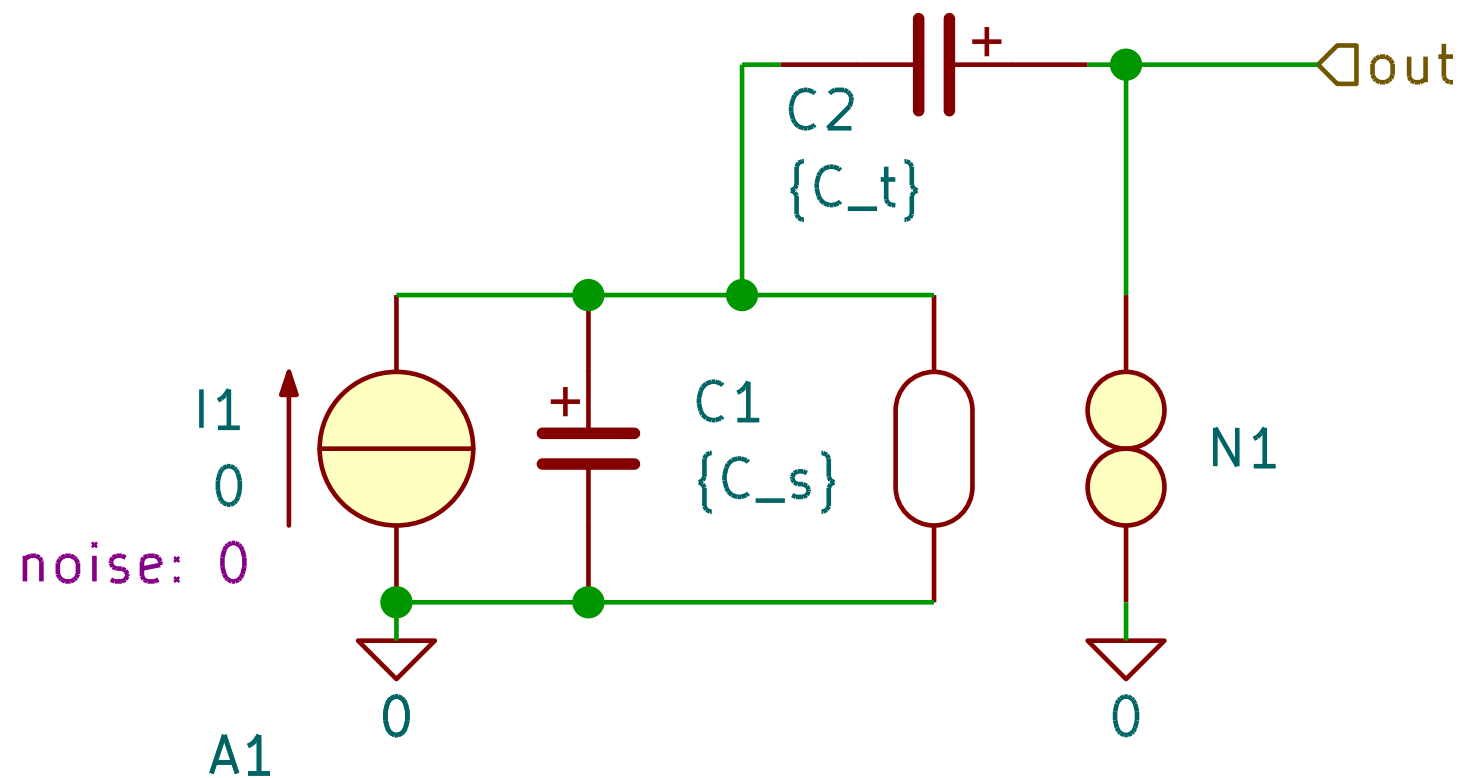


1. Select CMOS process and fit EKV parameters to BSIM
2. Create KiCAD amplifier circuit with nullor as controller
3. Define noise requirements (frequency range and budgets)
4. Define technology requirements  
(channel type, minimum and maximum geometry)
5. Define circuit requirements  
(inversion coefficient or gm/ID ratio, and current budget)
6. Run the design automation script
7. Select one valid option for design

SLiCAP replaces the nullor with an N-channel or a P-channel noisy nullor and evaluates  $W$ ,  $L$ , and  $I_{DS}$  for six scenarios for the selected inversion coefficient or gm/ID ratio:

1. Minimum noise at maximum inversion level
2. Minimum current to meet the noise specification
3. Minimum cut-off frequency to meet the noise specification

# SLiCAP design automation



.detector V\_out

A2

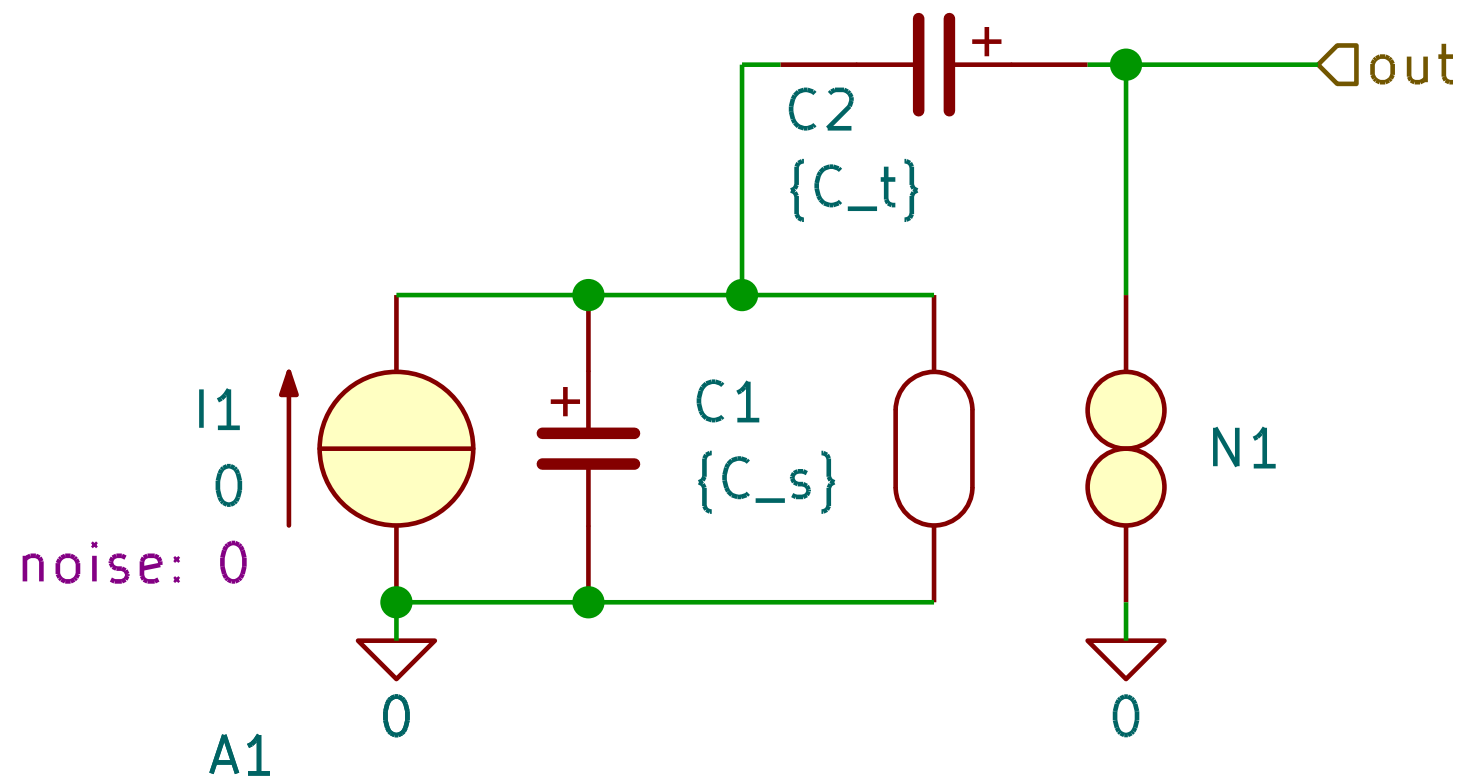
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SLiCAP replaces the nullor with an N-channel or a P-channel noisy nullor and evaluates  $W$ ,  $L$ , and  $I_{DS}$  for six scenarios for the selected inversion coefficient or gm/ID ratio:

1. Minimum noise at maximum inversion level
2. Minimum current to meet the noise specification
3. Minimum cut-off frequency to meet the noise specification
4. Minimum product of  $g_m$  and  $c_{iss}$  to meet the noise specification

# SLiCAP design automation



.detector V\_out

A2

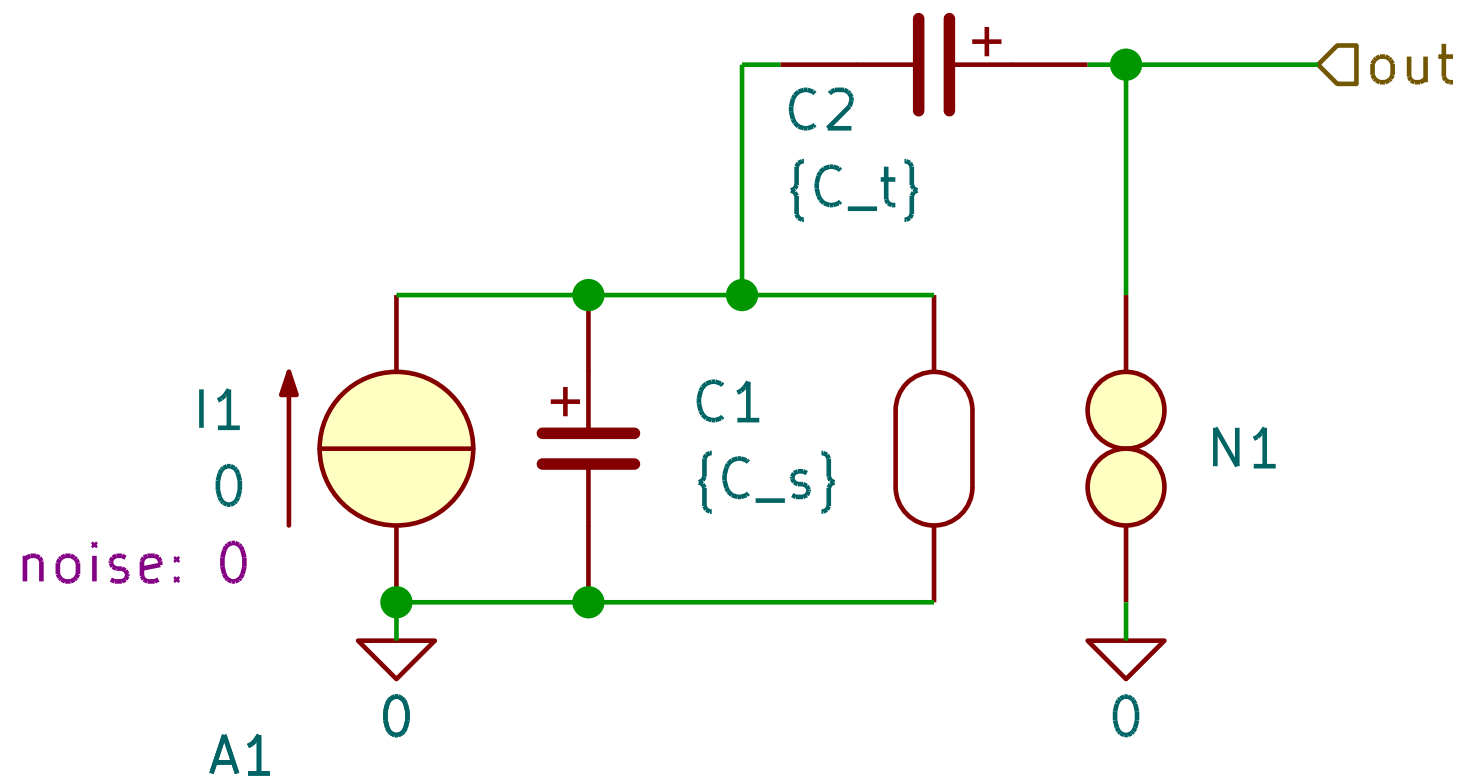
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SLiCAP replaces the nullor with an N-channel or a P-channel noisy nullor and evaluates  $W$ ,  $L$ , and  $I_{DS}$  for six scenarios for the selected inversion coefficient or gm/ID ratio:

1. Minimum noise at maximum inversion level
2. Minimum current to meet the noise specification
3. Minimum cut-off frequency to meet the noise specification
4. Minimum product of  $g_m$  and  $c_{iss}$  to meet the noise specification
5. Minimum area at a given current budget to meet the noise specification

# SLiCAP design automation



`.detector V_out`

`A2`

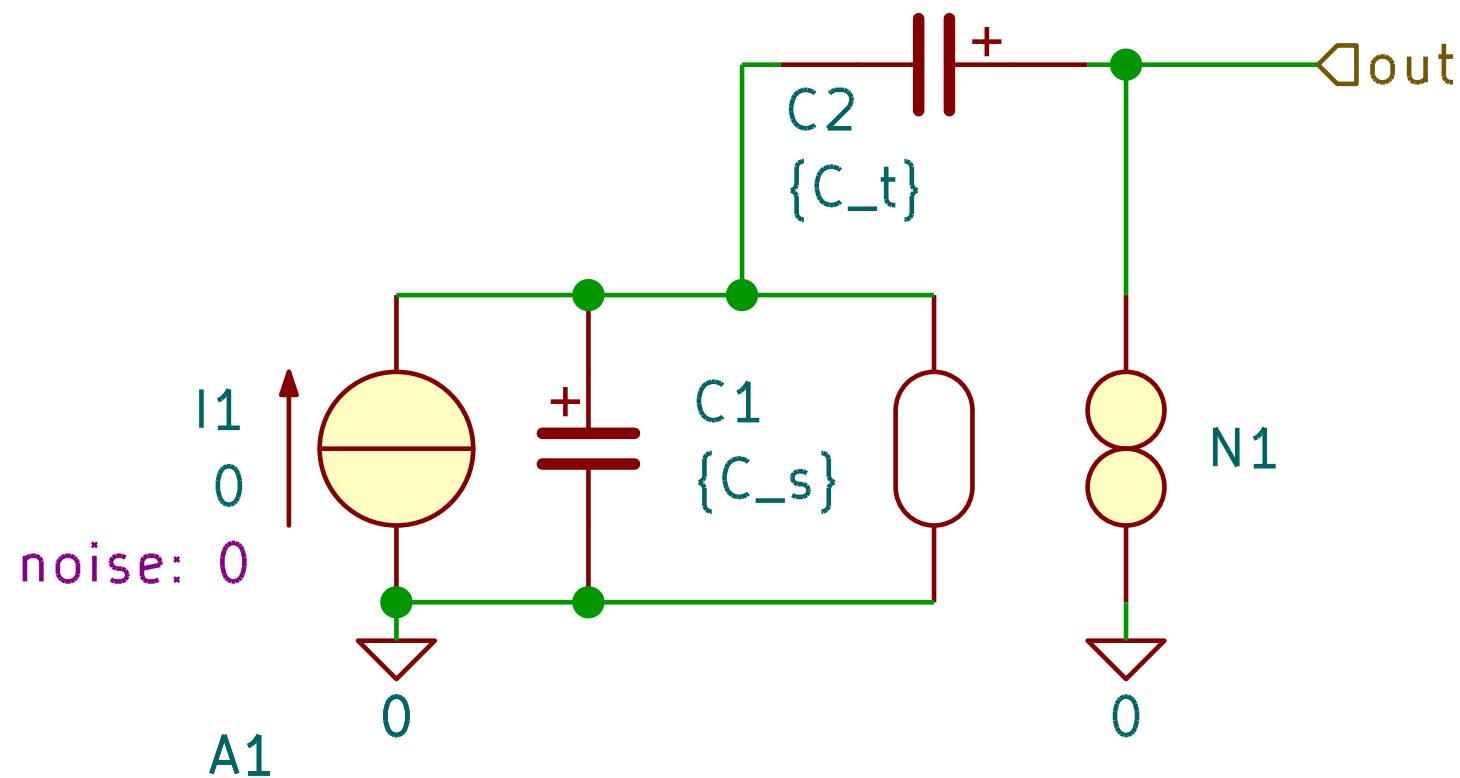
`.param C_s=1p C_t=0.2p IG=0`

1. Select CMOS process and fit EKV parameters to BSIM
2. Create KiCAD amplifier circuit with nullor as controller
3. Define noise requirements (frequency range and budgets)
4. Define technology requirements  
(channel type, minimum and maximum geometry)
5. Define circuit requirements  
(inversion coefficient or  $g_m/I_D$  ratio, and current budget)
6. Run the design automation script
7. Select one valid option for design

SLiCAP replaces the nullor with an N-channel or a P-channel noisy nullor and evaluates  $W$ ,  $L$ , and  $I_{DS}$  for six scenarios for the selected inversion coefficient or  $g_m/I_D$  ratio:

1. Minimum noise at maximum inversion level
2. Minimum current to meet the noise specification
3. Minimum cut-off frequency to meet the noise specification
4. Minimum product of  $g_m$  and  $c_{iss}$  to meet the noise specification
5. Minimum area at a given current budget to meet the noise specification
6. Maximum area at a given current budget to meet the noise specification

# SLiCAP design automation



`.detector V_out`

`A2`

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1. Select CMOS process and fit EKV parameters to BSIM
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2. Minimum current to meet the noise specification
3. Minimum cut-off frequency to meet the noise specification
4. Minimum product of  $g_m$  and  $c_{iss}$  to meet the noise specification
5. Minimum area at a given current budget to meet the noise specification
6. Maximum area at a given current budget to meet the noise specification