Structured Electronic Design

Introduction to Frequency Compensation

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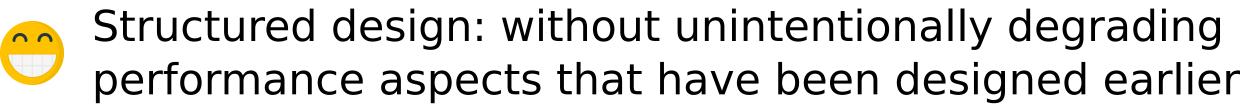
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Introduction

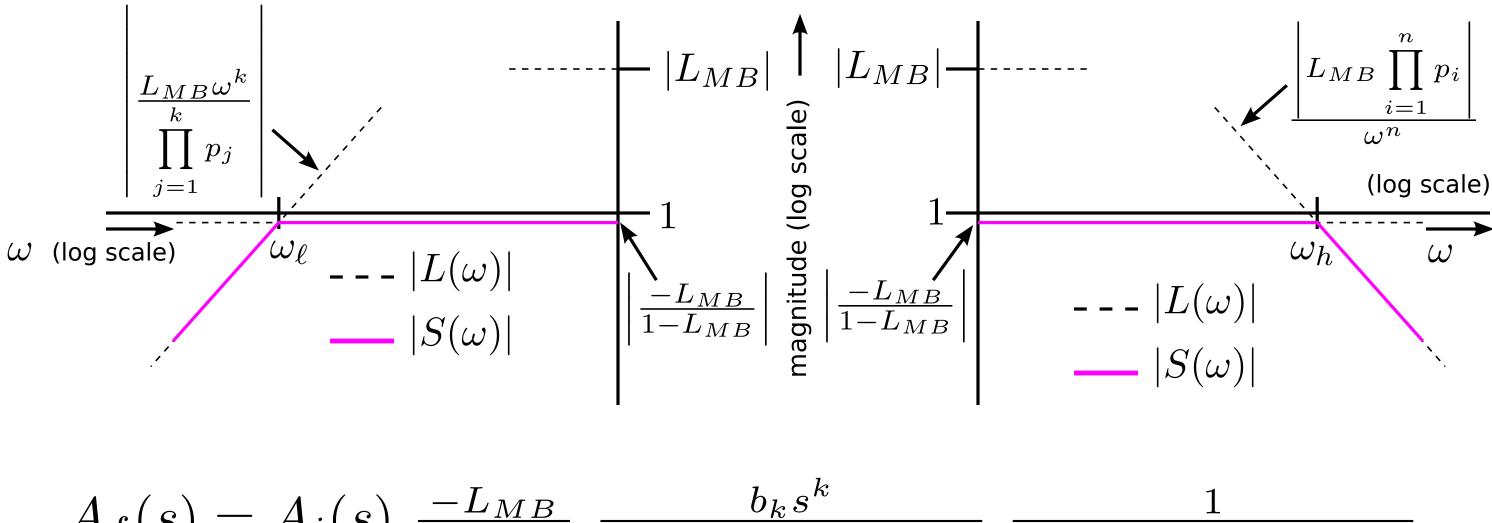


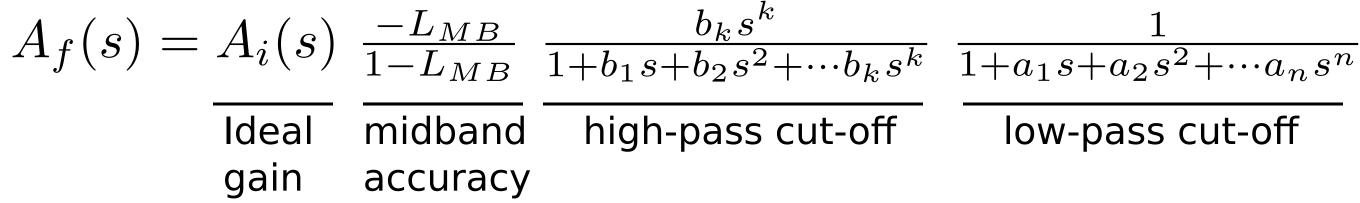


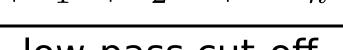


Design approach

Independent correction of high-pass and low-pass cut-off behavior







Techniques

- ✓ 1. Insertion of phantom zeros
- \times 2. 'Pole-splitting' by increasing the interaction between two poles
- × 3. 'Pole-splitting' through pole-zero canceling
- × 4. 'Resistive broadbanding' by exchanging a pole frequency with midband loop gain

Strategies

- \checkmark 1. Maintain the bandwidth designed at an ealier stage a. The obtained bandwidth is adequate b. There is no margin to reduce it
- × 2. Exchange bandwidth of ideal transfer with that of servo function a. The obtained bandwidth is much more than required b. The bandwidth of the ideal gain can be reduced × 3. Reduce the bandwidth of the loop gain
 - a. The obtained bandwidth is more than required b. The number of dominant poles is too large to deal with